

Operator's Manual

CONTROLLER ISOBUS VT

Instruction book - SW 3.XX

67023603 - Version 1.10 US - 06.2015

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Welcome letter



Dear New HARDI® Owner,

Thank you for purchasing your new HARDI® product and welcome to the ever-increasing family of proud HARDI® owners.

HARDI[®] is the leading sprayer company in offering growers strong, reliable products made for the widest range of applications worldwide. Quality, reliability, and resale value make the HARDI[®] product line the preferred product line of customers both in North America as well as worldwide. Our guiding principle is to provide the highest level of customer satisfaction and long term value in the marketplace today. We have developed a very high level of customer loyalty in the marketplace which we are very proud of and strive every day to maintain and to continue to grow.

HARDI® is your specialist in spraying and we spend all of our time and keep all of our focus on spraying. We do not share our resources between other types of products or compromise on anything in providing the best quality sprayers to the market today. We can provide the latest in technology with our products if desired, or allow them to operate with the technology that you already use on other products in most cases. You get to decide that, and what best suits your needs. We feel that you, our customer, are the best suited to answer that question for your operation. Either way, you decide, and we will try and help make it happen for you.

Our broad spectrum of product offerings, from the ruggedly simple models we build to our highly sophisticated models, the built-in HARDI® strength and reliability ensures a low cost of ownership. HARDI® sprayers are all based on a functional design concept of being as simple to operate as possible and to meet our customers' requirements for all their application needs.

Please take the time to thoroughly read the Operator's Manual before using your equipment. You will find many helpful hints as well as important safety and operation information.

Some of the features on your HARDI® sprayer were suggested by growers. There is no substitute for "on farm" experience and we invite your comments and suggestions. If any portion of this instruction book remains unclear after reading it, contact your HARDI® dealer or service personnel for further explanation before using the equipment.

For Product, Service or Warranty Information please contact your local HARDI® dealer.

- Please use the HARDI® Customer Service number: 1-866-770-7063
- Or send your email to CUSTSERV@hardi-us.com

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Sincerely,

Wayne Buchberger President

1 - Welcome

Operator safety

Symbols

These symbols are used throughout the book to designate where the reader needs to pay extra attention.

This symbol means ATTENTION. This guides to better, easier and safer operation of your sprayer!



This symbol means DANGER. Be very alert as your safety is involved!



This symbol means WARNING. Be alert as your safety can be involved!



This symbol means NOTE.

Precautions

Note the following recommended precautions and safe operating practices before using the sprayer.

General info



Read and understand this instruction book before using the equipment. It is equally important that other operators of this equipment read and understand this book.



If any portion of this instruction book remains unclear after reading it, contact your HARDI® dealer for further explanation before using the equipment.



Keep children away from the equipment.



Press the keys with the underside of your finger. Avoid using your fingernail.

Local law may demand that the operator is certified to use spray equipment. Adhere to the law.



Tractor driver's seat is the intended working place during operation.

Service



Test with clean water prior to filling with chemicals. Rinse and wash equipment after use and before servicing.



Never service or repair the equipment while it is operating. Always replace all safety devices or shields immediately after servicing.



Turn electrical power off before connecting and disconnecting the display and transducers, servicing or using a battery charger.



If an arc welder is used on the equipment or anything connected to the equipment, disconnect power leads before welding. Remove all flammable or explosive material from the area.



Do not use a high pressure cleaner to clean the electronic components.

2 - Safety notes

Introduction

About the ISOBUS VT system

The ISOBUS VT is for use in agricultural and horticultural production. The components are developed to last many years under agricultural conditions.

The system has a non-volatile memory without battery which simplifies storage. All parameters in the menus are saved in the memory and are not lost when the power is disconnected.

| Main components | Location |
|------------------------------|------------------------|
| ISOBUS terminal | Tractor/Self-propelled |
| HC 6300 Grip | Tractor/Self-propelled |
| HC 6400 SetBox/Spray Center | Tractor/Self-propelled |
| HC 6100 JobCom | Sprayer/Self-propelled |
| HC 6200 FluidBox/Outside Box | Sprayer/Self-propelled |

The transducers utilized are chosen for long service life and good signal quality. The speed and flow transducers have a builtin diode that will flash to indicate when it's functioning, to aid servicing.

Optional transducers include pressure and revolutions readout. Other options include a 12 Volt printer.

Working pictures will be shown in different colors, depending on the function used.

Display readouts

Among many possible display readouts, are:

- Volume rate.
- Speed.
- Liquid rate per minute.
- Total covered area.
- Total volume sprayed.
- 99 trip registers. It includes a total register that summarizes data from the 98 trip registers.



The system is also compatible with Variable Rate Application (VRA) and is prepared for communication with Precision Farming tools (e.g. HARDI® AutoSectionControl). Data dump of registers and configuration to a personal computer are possible.

Functions include

- Correct area with closure of up to 13 spray boom sections.
- Many alarm functions and possibility for audio/visual alarm etc.
- Many warnings depending on operation. Alarms and warnings is shown in the bottom left 1/4 corner of the display on some VT screens. HC 9500 will show alarms in top of the screen.

System description

Overall description

The precise wiring setup can vary, depending on the terminal mounted.

ISOBUS system (trailed)



ISOBUS system (self-propelled)



- A. HC 9500 or VT Terminal.
- **B.** SetBox and Grip.
- C. GPS antenna (optional).
- **D.** IBBC connector.
- E. Vehicle bus.
- F. ISOBUS.
- G. FluidBox (i-sprayers only).

- H. JobCom (Implement ECU).
- I. Center section junction box.
- J. Hydraulics block.
- K. AutoHeight UC5.
- L. ISOBUS bridge.
- M. Cabin connector.

Terminals and boxes

Types of terminals

This software can run with two types of ISOBUS display terminals.

ISOBUS terminals with physical buttons

ISO terminals with physical function buttons, e.g. the Massey Ferguson terminal shown.

- Conventional or touch screen and physical buttons.
- Function buttons are graphical but are operated by physical buttons on the terminal.
- The software runs as a Virtual Terminal (VT) into the terminal software.

ISOBUS terminals with touchscreen interface

 $\mathsf{HARDI}^{\otimes}\,\mathsf{HC}\,9500\,\mathsf{or}\,similar\,\mathsf{ISO}\,terminals\,with\,touchscreen\,interface.$ The HC 9500 is shown.

- Touchscreen and no buttons (except ON/OFF).
- Function buttons are graphical and operated by pressing the touch screen.
- The software runs as a Virtual Terminal (VT) into the terminal software.

ISOBUS Terminal layout

The ISOBUS terminal layout is described as follows:

ISOBUS virtual terminal buttons

- 1. Scroll up, increase a value or volume rate.
- 2. Enter menu.
- 3. Scroll down, decrease a value or volume rate.
- 4. Preset keys.
- 5. Soft menus.

- 6. Escape a menu.
- 7. Scroll up.
- 8. Enter menu or confirm a value.
- 9. Scroll down.

Display symbols

These symbols are common on VT (Virtual Terminal) displays.

- 1. The 1st Line is for status symbols, register number and alarm number. All status symbols will be displayed here.
- ATTENTION! If an error occurs, alarm/warning error number will be shown instead of register number. The alarm/warning number can be recognized by the exclamation sign in front of the number.
 - 2. The 2nd Line is for boom status, foam marker and end nozzle indications.
 - 3. ISOBUS: The bottom half has 6 boxes with selectable information.
- **1** NOTE! See "Menu 2.1 Display readout" on page 6.1 for setup of the display readouts in the bottom half of the terminal display.

1st line status icons

A. Preset keys

Vital information while spraying is quick and easy to access.

Pressing the button will enter a submenu with the preset keys.

B. Soft keys

Soft keys control optional features. Press the soft key button to activate a submenu with further features.

ATTENTION! The number of levels in the soft key menu system depends on the number of functions - see also "Soft keys menu tree" below.

C. Navigation keys

The navigation keys are initially used for set up in the menu system by coding in values. The navigation keys can change the volume rate in a set percentage or fixed volume rate. Other keys appear as needed on the ISOBUS Terminal.

| ISOBUS | | Description |
|--------|---|--|
| | This key appears whenever necessary at respective menus, etc. | Used to escape back to previous screen. |
| ESC | See "ESC key for ISOBUS terminals" on page 6.1 for setup of this button. | |
| | This key appears whenever necessary at respective menus, etc. | Used to scroll up. |
| ◄┛ | This key appears whenever necessary at respective menus, etc. | Used to enter a menu or confirm a value. |
| ↓ | This key appears whenever necessary at respective menus, etc. | Used to scroll down. |
| CLR | This is normally a key in the standard numeric keypad of the specific terminal. | Used to clear a value or register. |

D. Numeric keys

The keys will be the standard numeric keypad for the specific ISOBUS terminal.

Soft keys menu tree

| LEVEL 1 | | LEVEL 2 | | LEVEL 3 | | LEVEL 4 |
|---------|---------------|---------|--------------|---------|-------------|---------|
| ICON | FUNCTION | ICON | FUNCTION | ICON | FUNCTION | |
| | F1 EndNozzles | | F1 Left ON | | Work screen | |
| | | | F2 Left OFF | | | |
| | | | F3 Right OFF | | Work screen | |
| | | | F4 Right OFF | | | |

SetBox

The SetBox controls secondary functions. The keys are grouped into control areas to simplify operator understanding.

1 NOTE! Self-propelled sprayers do not have a SetBox as the controls are built-in to the cabin.

- 1. Power ON/OFF.
- 2. Pendulum unlock.
- 3. Pendulum lock.
- 4. Inner wing fold.
- 5. Inner wing unfold.
- 6. 1st outer wing fold.
- 7. 1st outer wing unfold.
- 8. 2nd outer wing fold.
- 9. 2nd outer wing unfold.
- 10. Automatic volume rate selector.
- 11. Manual pressure control.
- 12. Foam marker regulation.
- 13. Foam marker Left/Right selector.
- 14. DynamicCenter adjustment (increments).
- **15.** DynamicCenter outer positions 1 or 5.
- 16. Optional function A-B.
- 17. HeadlandAssist automatic.
- 18. HeadlandAssist boom align.
- 19. SafeTrack manual control (if installed).
- 20. SafeTrack align selector (if installed).
- 21. SafeTrack automatic selector (if installed).

ATTENTION! Button 1 has different function on ISOBUS sprayers as this turns the JobCom ON/OFF.

ATTENTION! Buttons 17 and 18 can have different functions if the sprayer is equipped with AutoHeight.

ATTENTION! The Grip cannot be switched ON/OFF separately. It is automatically switched ON when tractor power is turned ON (ISOBUS).

HC 6300 Grip

The Grip is an ergonomic remote unit that can be easily mounted inside the tractor cabin. All common functions required during normal spraying can be operated with the Grip. Also the Grip controls some optional functions.

- ATTENTION! The Grip cannot be switched ON/OFF separately. It is automatically switched ON when tractor power is turned ON (ISOBUS).
- A. Status LED.
- B. Boom section controls (up to 13).
- C. Main ON/OFF.
- D. Tilt.
- E. Boom height.
- F. Boom slant.
- G. Not used.
- H. TWIN presets.

General keystrokes

The first steps to choose a menu are shown below. See also "Full menu structure" on page 3.15.

Menu selection

- 1. Press {Menu} Virtual Terminal button to proceed into the menu.
- 2. Navigate to desired submenu using arrows.
- 3. In the menu, the current selection is marked with a colored bar.
- 4. Move the menu colored bar up and down by using the {up} and {down} arrows.

NOTE! A maroon colored bar indicates current setting.

5. Confirm selection by pressing the enter arrow.

1

ATTENTION! Press {ESC} to leave the menu without changing values.

NOTE! There is help text for each menu in the bottom of the display. The displayed help text corresponds to the location of the colored bar on the Virtual Terminal.

Menu editing example: Tank contents ISOBUS VT

1. At main ISOBUS VT screen select {Menu} to enter menus.

2. With "Daily Settings" highlighted, select {Enter} to confirm.

3. Scroll to "Tank contents" with {up} or {down} arrows and select enter to confirm.

4. Select the value field to enter a value.

5. Enter the new tank contents value on the numeric key pad and select check mark to confirm.

| 7 | 8 | 9 | |
|---|------|---|--|
| 4 | 5 | 6 | |
| 1 | 2 | 3 | |
| 0 | - 12 | - | |

Extended menu

This menu has been set up by your HARDI® Service center. It contains parameters that are typically set only once, normally before the Controller is used.

• For ISOBUS terminals the extended menu is accessible from menu 2.8 and requires a pin code to enter.

ATTENTION! Unless instructed, do not tamper with the settings and values in these menus. Doing so may void warranty.

Functions

Auto functions general info

The Soft key buttons are used for the End Nozzle functions.

ATTENTION! Refer to "B. Soft keys" on page 3.6 for information about how to enter the soft keys.

End nozzles (Fence line) (optional)

If End nozzles/Bi-jet are fitted, set the value to the equivalent coverage by the boom nozzles. E.g. End nozzle coverage is 5 feet. This is equal to [03 Boom nozzles]. Choose End Nozzles by pressing F1.

- When end nozzle is active, it will be shown in the display with two icons at the ends of the boom line.
- Set up of end nozzles/Bi-jet can be done from menu 3.3.4.

ATTENTION! It is important that the volume applied from the end nozzle or Bi-jet matches the volume applied under the boom. This is a comparison of volume per minute per length. (Liter/min/meter).

When the end nozzle or Bi-jet is active, the area covered and volume sprayed is calculated and registered. If "Active boom size" is displayed, it will show an increase when the end nozzle or Bi-jet is activated.

DynamicFluid4 pressure regulation

Traditional fluid regulation starts when the nozzles are opened. With DynamicFluid4 the regulation is a continuous process that continues even if the nozzles are closed. Two ceramic discs regulate the pressure and ensures quick reaction and zero leakages. Sprayer speed, P.T.O. RPM and number of sections activated are parameters used, and the benefit is more precise application rates from the second the sprayer begins spraying.

The DynamicFluid4 uses feed forward technology based on 5 sensors that feed the JobCom computer with data necessary for optimal regulation. It auto-primes at start-up, starts and moves the valve towards the final position immediately after the operator makes changes. E.g. when section valves are opened or closed, the regulation valve is started the same time the section valve motors are started. This avoids overpressure situations e.g. after running empty and refill of main tank.

The 5 sensors are also back-up for each other and ensures the system can continue regulation even if one or more sensor signals fail. Sensors used are:

- Sprayer speed sensor
- Flow sensor
- Pressure sensor
- Pump r.p.m. sensor
- Regulation valve opening angle sensor

The DynamicFluid4 pressure regulation features are:

- Very fast and accurate regulation when all sensors are ok, setup in menus are correct and pump, filters and valves are in good condition.
- Quick reacting valve when sections are turned ON/OFF and at speed changes.
- Optimized AutoSectionControl feature that predicts when boom sections will open and nozzle pressure.
- Optimized for different P.T.O. systems.
- Nozzle surveillance. No setup or tuning required for nozzle change.
- Warning in display if failures occur on boom plumbing, such as severe clogging of line or nozzle filters or large leakages on hoses and fittings.
- All functions continue working, although with degraded performance (Limp home modes), if:

Faults occur in fluid system, e.g. pump defects, clogged filters, leaking valves.

- Sensor failure appears on pressure sensor, flow sensor or RPM sensor.
- There is wrong setup of sprayer data in menus.
- Emergency mode if angle sensor or speed sensor fails.

Screen icons

The sprayer driver selects one of three modes Auto, Manual or Increment steps. The sprayer computer detects one of three regulation modes Drop, Question mark or calibration jug. This makes 9 modes in total.

| Auto | Manual | Increment steps | |
|---|--|---|--|
| When Automatic Volume Rate button is pressed on the SetBox. | When one of the Manual pressure control buttons is pressed on the SetBox. | When the Volume Rate is changed in steps with %-up or %-down buttons on the Terminal. | |
| τΠ | 511 | 11 | Calibration jug |
| л. Л. | <u> </u> | о <u>~</u> п. | There is flow to section valves. |
| ouio | | /0 | Nozzle size (L/min at 3 bar) has been calculated. |
| ~ | | | Drop |
| | | % | There is no flow to section valves. |
| GUIO | | | The pump is not started or the pressure SmartValve is set to other function than spraying. |
| 0 | 2 | 0 | Question mark |
| auto | | % [!] | There is flow to section valves but pressure and flow has not yet been stable, therefore the nozzle size (L/min at 3 bar) has not been calculated. |
| | | | The system uses the previously stored nozzle size. |

SafeTrack (Trailed sprayers only)

SafeTrack is a steering mechanisms for the trailed HARDI® sprayers. When using a track system, sprayer stability is a common concern. Many factors influence the sprayer and conditions where the sprayer might tip over have to be dealt with.

The factors that the driver can influence with are

- Driving behavior
- Field conditions
- Tire width
- Tire pressure

Read sprayer's instruction book for further information. If unsafe driving occurs, an alarm will be triggered and the sprayer will align. Be aware that the alarm cannot be turned off as long as unsafe driving still occurs!

ATTENTION! If necessary, the level of security can be adjusted - please contact your local HARDI® dealer.

DANGER! The system has been calibrated during driving on flat fields. Special attention should be made when driving in hilly conditions.

DANGER! When driving on fields with deep tracks, then the speed must be decreased.

HARDI® AutoSectionControl (optional)

HARDI® AutoSectionControl will:

- manage the sections when driving over sprayed area, like into a headland or wedge or around obstacles like trees, etc.
- automatically record the area sprayed, when spraying.

In a typical situation where the headland is sprayed first, HARDI® AutoSectionControl will now automatically close the sections if the operator passes over a sprayed area.

ATTENTION! Variable Rate Application needs to be enabled for AutoSectionControl to work - refer to "Menu 2.3 Variable Rate Application (VRA) / Remote / HARDI® AutoSectionControl" on page 6.3.

ATTENTION! For more information about AutoSectionControl, see the AutoSectionControl instruction book. On ISOBUS terminals AutoSectionControl can be an integrated part - if so, refer to the ISOBUS terminal instruction book.

Menus

Full menu structure

1

NOTE! Blank fields are menus without name or description.

NOTE! Menus marked with a grey box are not for ISOBUS terminals.

| Menu number | Menu name | Description / Help text |
|---------------|----------------------------|---|
| 1 | Daily settings | Most used settings e.g. desired rate, tank contents and register number |
| 1. 1 | Volume rate | Use arrow keys or numeric keys to set the desired volume rate |
| 1. 2 | Tank contents | To change displayed tank contents. Use arrow keys or numeric keys to set |
| 1. 3 | Select register | Use register 1 to 99 for job. Scroll to register, then press Enter to show data |
| 1. 3. 1 | | |
| 1.3.1.1 | Show register spray data 1 | Press C for 5 sec to reset register. Enter to see screen 2, ESC to leave |
| 1. 3. 1. 1. 1 | Start date | |
| 1. 3. 1. 1. 2 | Start time | |
| 1. 3. 1. 1. 3 | End date | |
| 1. 3. 1. 1. 4 | End time | |
| 1. 3. 1. 2 | Show register spray data 2 | Press C for 5 sec to reset register, Enter to see screen 1, ESC to leave |
| 1. 3. 1. 2.1 | Volume applied | |
| 1. 3. 1. 2.2 | Area covered | |
| 1. 3. 1. 2.3 | Average spray speed | |
| 1. 3. 1. 2.4 | Maximum spray speed | |
| 1. 3. 1. 2.5 | Travelled spray dist | |
| 1. 3. 1. 2.6 | Time used spraying | |
| 1. 3. 1. 2.7 | Work rate | |
| 1. 3. 1. 2.8 | Average volume rate | |
| 1. 4 | Volume rate: Preset high | Rate selected with1 press on the arrow up-key |
| 1. 5 | Volume rate: Preset low | Rate selected with1 press on the arrow down-key |

| 2 | | Setup | Customizing of display, automatic functions, clock, alarms, registers, etc |
|----|-------------|-------------------------|--|
| 2. | 1 | Display readout | Customizes the 4 small display readouts |
| | 2. 1. 1 | Show upper middle | |
| | 2.1.1.01 | Programmed volume rate | Shows Programmed volume rate |
| | 2.1.1.02 | Boom flow | Boom flow rate per minute sprayed out through the boom |
| | 2.1.1.03 | time | Actual time |
| | 2.1.1.04 | Work rate | Rate shown in hectare per hour or acre per hour |
| | 2.1.1.05 | Actual volume rate | Actual rate in liter per hectare or gallon per acre |
| | 2.1.1.06 | Tank contents | Main tank contents |
| | 2.1.1.07 | Speed | Driving speed |
| | 2.1.1.08 | Volume sprayed | Readouts for Volume sprayed in currently active register |
| | 2.1.1.09 | Area sprayed | Readouts for Area sprayed in currently active register |
| | 2.1.1.10 | Active boom size | Active boom size including end nozzle |
| | 2.1.1.11 | Pressure | Displays spray pressure if sensor is fitted |
| | 2.1.1.12 | Fan speed | Displays Twin fan speed if sensor is fitted |
| | 2.1.1.13 | Wind Speed | Displays wind speed if sensor is fitted |
| | 2.1.1.14 | Pendulum lock status | Displays reading of pendulum lock sensor if fitted |
| | 2.1.1.15 | Pendulum unlock status | Displays reading of pendulum unlock sensor if fitted |
| | 2.1.1.16 | Dynamic center position | Displays Dynamic center position sensor if fitted |
| | 2.1.1.17 | Spray pump rev | Displays revolutions if sensor is fitted |
| | 2.1.1.18 | Extra sensor 1F | Readout from extra sensor 1 frequency |
| | 2.1.1.19 | Extra sensor 2F | Readout from extra sensor 2 frequency |
| | 2.1.1.20 | Extra sensor 3A | Readout from extra sensor 3 analog |
| | 2.1.1.21 | Extra sensor 4A | Readout from extra sensor 4 analog |
| | 2. 1. 1. 22 | Voltmeter | Displays system voltage. Useful when fault finding |
| | 2.1.1.23 | Agitation | Agitation valve opening |

| 2. 1. 1. 24 | RinseTank content | RinseTank calculated content |
|-------------|------------------------------------|--|
| 2. 1. 1. 25 | Slant angle | Headland assist angle sensor |
| 2. 1. 1. 26 | Boom height | Headland assist height sensor |
| 2. 1. 1. 27 | Reserved | RR |
| 2. 1. 1. 28 | Reserved | RR |
| 2.1.1.29 | Reserved | RR |
| 2.1.1.30 | Reserved | RR |
| 2. 1. 1. 31 | Reserved | RR |
| 2. 1. 1. 32 | Reserved | RR |
| 2. 1. 1. 33 | Nozzle size flow at 3 bar (45 psi) | Calculated nozzle flow at 3 bar (45 psi) |
| 2. 1. 1. 34 | | |
| 2. 1. 1. 35 | | |
| 2.1.1.36 | | |
| 2.1.1.37 | PF bus + | Voltage on PrimeFlow databus + |
| 2.1.1.38 | PF bus - | Voltage on PrimeFlow databus - |
| 2. 1. 2 | Show upper right | |
| 2. 1. 2. 01 | Programmed volume rate | Shows Programmed volume rate |
| 2.1.2.02 | Boom flow | Boom flow rate per minute sprayed out through the boom |
| 2.1.2.03 | time | Actual time |
| 2. 1. 2. 04 | Work rate | Rate shown in hectare per hour or acre per hour |
| 2.1.2.05 | Actual volume rate | Actual rate in liter per hectare or gallon per acre |
| 2.1.2.06 | Tank contents | Main tank contents |
| 2. 1. 2. 07 | Speed | Driving speed |
| 2. 1. 2. 08 | Volume sprayed | Readouts for Volume sprayed in currently active register |
| 2.1.2.09 | Area sprayed | Readouts for Area sprayed in currently active register |
| 2. 1. 2. 10 | Active boom size | Active boom size including end nozzle |
| 2. 1. 2. 11 | Pressure | Displays spray pressure if sensor is fitted |
| 2. 1. 2. 12 | Fan speed | Displays Twin fan speed if sensor is fitted |
| 2. 1. 2. 13 | Wind Speed | Displays wind speed if sensor is fitted |
| 2.1.2.14 | Pendulum lock status | Displays reading of pendulum lock sensor if fitted |
| 2.1.2.15 | Pendulum unlock status | Displays reading of pendulum unlock sensor if fitted |
| 2.1.2.16 | Dynamic center position | Displays Dynamic center position sensor if fitted |
| 2.1.2.17 | Spray pump rev | Displays revolutions if sensor is fitted |
| 2.1.2.18 | Extra sensor 1F | Readout from extra sensor 1 frequency |
| 2.1.2.19 | Extra sensor 2F | Readout from extra sensor 2 frequency |
| 2.1.2.20 | Extra sensor 3A | Readout from extra sensor 3 analog |
| 2.1.2.21 | Extra sensor 4A | Readout from extra sensor 4 analog |
| 2.1.2.22 | Voltmeter | Displays system voltage. Useful when fault finding |
| 2.1.2.23 | Agitation | Agitation valve opening |
| 2.1.2.24 | RinseTank content | RinseTank calculated content |
| 2.1.2.25 | Slant angle | Headland assist angle sensor |
| 2.1.2.26 | Boom height | Headland assist height sensor |
| 2.1.2.27 | Reserved | RR |
| 2.1.2.28 | Reserved | RR |
| 2.1.2.29 | Reserved | RR |
| 2.1.2.30 | Reserved | RR |
| 2.1.2.31 | Reserved | RR |
| 2.1.2.32 | Reserved | RR |
| 2.1.2.33 | Nozzle size flow at 3 bar (45 psi) | Calculated nozzle flow at 3 bar (45 psi) |
| 2.1.2.34 | | |
| 2.1.2.35 | | |
| 2.1.2.36 | | |
| 2.1.2.37 | PF bus + | Voltage on PrimeFlow databus + |
| 2. 1. 2. 38 | PF bus - | Voltage on PrimeFlow databus - |
| 2. 1. 3 | Show lower middle | |
| 2. 1. 3. 01 | Programmed volume rate | Shows Programmed volume rate |
| 2.1.3.02 | Boom flow | Boom flow rate per minute sprayed out through the boom |

| 2.1.3.03 | time | Actual time |
|-------------|------------------------------------|--|
| 2.1.3.04 | Work rate | Rate shown in hectare per hour or acre per hour |
| 2.1.3.05 | Actual volume rate | Actual rate in liter per hectare or gallon per acre |
| 2.1.3.06 | Tank contents | Main tank contents |
| 2.1.3.07 | Speed | Driving speed |
| 2.1.3.08 | Volume sprayed | Readouts for Volume sprayed in currently active register |
| 2.1.3.09 | Area sprayed | Readouts for Area sprayed in currently active register |
| 2.1.3.10 | Active boom size | Active boom size including end nozzle |
| 2.1.3.11 | Pressure | Displays spray pressure if sensor is fitted |
| 2.1.3.12 | Fan speed | Displays Twin fan speed if sensor is fitted |
| 2.1.3.13 | Wind Speed | Displays wind speed if sensor is fitted |
| 2.1.3.14 | Pendulum lock status | Displays reading of pendulum lock sensor if fitted |
| 2.1.3.15 | Pendulum unlock status | Displays reading of pendulum unlock sensor if fitted |
| 2.1.3.16 | Dynamic center position | Displays Dynamic center position sensor if fitted |
| 2.1.3.17 | Spray pump rev | Displays revolutions if sensor is fitted |
| 2.1.3.18 | Extra sensor 1F | Readout from extra sensor 1 frequency |
| 2.1.3.19 | Extra sensor 2F | Readout from extra sensor 2 frequency |
| 2.1.3.20 | Extra sensor 3A | Readout from extra sensor 3 analog |
| 2.1.3.21 | Extra sensor 4A | Readout from extra sensor 4 analog |
| 2.1.3.22 | Voltmeter | Displays system voltage. Useful when fault finding |
| 2.1.3.23 | Agitation | Agitation valve opening |
| 2.1.3.24 | RinseTank content | RinseTank calculated content |
| 2.1.3.25 | Slant angle | Headland assist angle sensor |
| 2.1.3.26 | Boom height | Headland assist height sensor |
| 2.1.3.27 | Reserved | RR |
| 2.1.3.28 | Reserved | RR |
| 2.1.3.29 | Reserved | RR |
| 2.1.3.30 | Reserved | RR |
| 2.1.3.31 | Reserved | RR |
| 2.1.3.32 | Reserved | RR |
| 2.1.3.33 | Nozzle size flow at 3 bar (45 psi) | Calculated nozzle flow at 3 bar (45 psi) |
| 2.1.3.34 | | |
| 2.1.3.35 | | |
| 2.1.3.36 | | |
| 2.1.3.37 | PF bus + | Voltage on PrimeFlow databus + |
| 2.1.3.38 | PF bus - | Voltage on PrimeFlow databus - |
| 2. 1. 4 | Show lower right | |
| 2.1.4.01 | Programmed volume rate | Shows Programmed volume rate |
| 2.1.4.02 | Boom flow | Boom flow rate per minute sprayed out through the boom |
| 2.1.4.03 | time | Actual time |
| 2.1.4.04 | Work rate | Rate shown in hectare per hour or acre per hour |
| 2.1.4.05 | Actual volume rate | Actual rate in liter per hectare or gallon per acre |
| 2.1.4.06 | Tank contents | Main tank contents |
| 2.1.4.07 | Speed | Driving speed |
| 2.1.4.08 | Volume sprayed | Readouts for Volume sprayed in currently active register |
| 2.1.4.09 | Area sprayed | Readouts for Area sprayed in currently active register |
| 2. 1. 4. 10 | Active boom size | Active boom size including end nozzle |
| 2.1.4.11 | Pressure | Displays spray pressure if sensor is fitted |
| 2. 1. 4. 12 | Fan speed | Displays Twin fan speed if sensor is fitted |
| 2. 1. 4. 13 | Wind Speed | Displays wind speed it sensor is fitted |
| 2. 1. 4. 14 | Pendulum lock status | Displays reading of pendulum lock sensor if fitted |
| 2. 1. 4. 15 | Pendulum unlock status | Displays reading of pendulum unlock sensor if fitted |
| 2. 1. 4. 16 | Dynamic center position | Displays Dynamic center position sensor if fitted |
| 2. 1. 4. 17 | Spray pump rev | Displays revolutions if sensor is fitted |
| 2. 1. 4. 18 | Extra sensor 1F | Readout from extra sensor 1 frequency |
| 2.1.4.19 | Evtra sensor /E | Readout from extra sensor / frequency |
| | | |

| 2. 1. 4. 21 | Extra sensor 4A | Readout from extra sensor 4 analog |
|---------------|------------------------------------|---|
| 2, 1, 4, 22 | Voltmeter | Displays system voltage. Useful when fault finding |
| 2, 1, 4, 23 | Agitation | Agitation valve opening |
| 2. 1. 4. 24 | RinseTank content | RinseTank calculated content |
| 2.1.4.25 | Slant angle | Headland assist angle sensor |
| 2. 1. 4. 26 | Boom height | Headland assist height sensor |
| 2. 1. 4. 27 | Reserved | RR |
| 2. 1. 4. 28 | Reserved | RR |
| 2, 1, 4, 29 | Reserved | RR |
| 2.1.4.30 | Reserved | RR |
| 2.1.4.31 | Reserved | RR |
| 2. 1. 4. 32 | Reserved | RR |
| 2.1.4.33 | Nozzle size flow at 3 bar (45 psi) | Calculated nozzle flow at 3 bar (45 psi) |
| 2.1.4.34 | | |
| 2.1.4.35 | | |
| 2.1.4.36 | | |
| 2.1.4.37 | PF bus + | Voltage on PrimeFlow databus + |
| 2.1.4.38 | PF bus - | Voltage on PrimeFlow databus - |
| 2. 1. 5 | Show ESC softkey to leave | ISObus terminal can have a separate ESC key or use an ESC softkey |
| 2.1.5.1 | Show ESC as softkey | Choose this to show ESC key as softkey on ISObus terminal |
| 2.1.5.2 | Do not show ESC as softkey | Choose this if ISObus terminal has a separate ESC key. |
| 2. 2 | AUTO functions | Set up for Auto ON/OFF, Foam marker, HeadlandAssist and optional A/B |
| 2. 2. 1 | Main ON/OFF | For automatic operation of the main ON/OFF function at a pre-set speed |
| 2. 2. 2 | Foam marker | To operate via the main ON/OFF function and automate side choice |
| 2.2.2.1 | Disable | It will only follow the manual setting of the switch on the SetBox |
| 2.2.2.2 | Same side | It will automatically activate the same side for race-track spraying |
| 2.2.2.3 | Change side | It will automatically change side for up and back spraying |
| 2. 2. 3 | Dual Line | To set up lower and upper trigger limits for the operation of line A and line B |
| 2.2.3.1 | Lower pressure level | Key in pressure level to switch Dual Line to smaller nozzles |
| 2. 2. 3. 2 | Upper pressure level | Key in pressure level to switch Dual Line to bigger nozzles |
| 2. 2. 3. 3 | From A to B speed level | Key in speed to switch Dual Line from A to B |
| 2. 2. 3. 4 | From B to A+B speed level | Rey in speed to switch Dual Line from B to A+B |
| 2. 2. 4 | HeadlandAssist setup | Boom lift and lower automatically when switching main ON/OFF function |
| 2. 2. 4. 1 | ON/OFF delay | Distance delay so the boom will lift of lower via the main ON/OFF |
| 2. 2. 4. 2 | | |
| 2.2.4.5 | Slant mirror and stops disable | Traditional clapt. No clapt mirror. No clapt in stops. |
| 2. 2. 4. 3. 1 | Slant mirror enable | Activate opposite slant at headlands. Slant in steps, not possible |
| 2. 2. 4. 3. 2 | Slant in steps enable | Activate slant in steps. Set step size in 2.2.4.4. Slant mirror not possible. |
| 2 2 5 | TWIN preset shift auto / man | Shifts automatically at main ON/OEE or manually at keypress |
| 2. 2. 5. 1 | Manual shift at keypress | Upon keypress it will change to the other preset value |
| 2. 2. 5. 2 | Auto shift at main ON/OFF | It will automatically change to the other preset value |
| 2.2.5.3 | TWIN controls disabled | TWIN fan, angle and preset controls are disabled |
| 2. 2. 6 | AutoAgitation select level | Powerful or soft no Agitation |
| 2.2.6.1 | Powerful AutoAgitation | Recommended for powder |
| 2.2.6.2 | Soft AutoAgitation | Recommended for liquid chemical |
| 2.2.6.3 | No agitation | Never use if sedimentation occurs. Recommended for liquid fertilizer. |
| 2.2.6.4 | Fixed agitation | Valve is positioned |
| 2.2.6.5 | Agitation switch | Switch increase or decrease agitation |
| 2. 2. 7 | AutoAgitation fixed level | Key in position of agitation valve for FluidBox key and fixed level |
| 2. 3 | VRA / Remote control | Variable Rate Application by RS232 Auto Section Control |
| 2. 3. 1 | VRA / Remote control disable | Variable Rate Application / Remote control disabled. Dish icon disappear |
| 2. 3. 2 | VRA / Remote control enable | by RS232 data port control enabled. Dish icon will be shown |
| 2. 4 | Set clock | Change date and clock time |
| 2. 4. 1 | Time format (12 or 24 hour) | Choose between a 12 hour or 24 hour clock |
| 2.4.1.1 | 12 hour format | You have chosen 12 hours as your time unit |
| 2.4.1.2 | 24 hour format | You have chosen 24 hours as your time |

| 2 4 2 | Set time | Set the actual time. Use arrow keys or numeric keys, then press Enter |
|------------------|----------------------------|---|
| 2. 4. 3 | Set date and month | Set date and month. Use arrow keys or numeric keys, then press Enter |
| 2.4.4 | Set year | Set vear Lise arrow keys or numeric keys then press Enter |
| 2 5 | Alarms | Different alarms can be set up. Choices will be listed |
| 2 5 01 | Volume rate alarm | Over or under application alarm |
| 2.5.01.1 | High volume rate limit | Over application warning for volume rate when over in 20 seconds |
| 2.5.01.7 | Low volume rate limit | Under application warning for volume rate when under in 20 seconds |
| 2.5.01.2 | Tank contents at minimum | Warning given when tank contents is below this volume |
| 2.5.02 | | High and low coray pressure alarm |
| 2. 5. 05 | High spray pressure limit | Warning given when spray pressure is above value |
| 2.5.03.1 | Low spray pressure limit | Warning given when under this pressure |
| 2.5.05.2 | Eow spray pressure innit | High and low r/min alarm |
| 2. 5. 04 1 | High fan revolutions limit | Warning given when over this value |
| 2.5.04.2 | | Warning given when under this value |
| 2.5.07.2 | | Speed maximum and minimum alarm |
| 2. 5. 05 | | Warning will be given if spraving over this value |
| 2.5.05.1 | Minimum speed value | Warning will be given if spraving under this value |
| 2.5.05.2 | Wind speed | Displays wind speed if sensor is fitted |
| 2 5 07 | PTO r/min alarm | PTO revolutions maximum and minimum alarm |
| 2. 5. 07 | Maximum value | Alarm value for the maximum revolutions on the PTO |
| 2. 5. 07. 1 | Minimum value | |
| 2. 5. 07. 2 | P/minute alarm | Provolutions maximum and minimum alarm |
| 2. 5. 08 1 | Maximum value | Alarm value for the maximum revolutions on the PTO |
| 2.5.08.2 | Minimum value | Alarm value for the minimum revolutions |
| 2.5.00.2 | Reserved | |
| 2. 5. 09 | Reserved | |
| 2.5.09.1 | Reserved | |
| 2. 5. 10 | R/minute alarm | Revolutions maximum and minimum alarm |
| 2.5.10 | R/minute max | Value (PPLI) maximum and minimum alarm |
| 2.5.11 | B/minute min | Value (Volt) maximum and minimum alarm |
| 2.5.15 | Sections OFE warning | Main ON/OEE is switched to ON and some sections are switched to OEE |
| 2.5.15 | Enabled | Press Enter to enable warning when sections are OFE |
| 2.5.15.1 | Disabled | Press Enter to disable warning |
| 2.5.16 | Audio level | Audio steps for alarm volume 0 is for no sound |
| 2.5.16.0 | Sound step 0 | $\Omega = \text{no sound 5 is maximum volume}$ |
| 2.5.16.1 | Sound step 1 | 0 = no sound, 5 is maximum volume |
| 2.5.16.2 | Sound step 2 | 0 = no sound, 5 is maximum volume |
| 2.5.16.3 | Sound step 2 | 0 = no sound, 5 is maximum volume |
| 2. 5. 16. 4 | Sound step 4 | 0 = no sound. 5 is maximum volume |
| 2.5.16.5 | Sound step 5 | 0 = no sound 5 is maximum volume |
| 2.6 | Begister names | Begister set up. Once done, a name can be copied and edited |
| 2. 6. 1 up to 99 | Register name | Toggle numeric keyboard to key in Register name |
| 2. 7 | Setup display | Setup for brightness, contrast and day/night colors |
| 2, 7, 1 | Choose day/night colors | Color change makes the display easier to read at day and night |
| 2. 7. 1. 1 | Day colors | Select this for day-time spraving Black text on white background |
| 2. 7. 1. 2 | Night colors | Select this for night-time spraying White text on black background |
| 2. 7. 2 | Setup brightness | Brightness can be stepped |
| 2. 7. 2. 1 | High brightness | Maximum setting |
| 2. 7. 2. 2 | Medium | Medium setting |
| 2. 7. 2. 3 | Low brightness | Minimum setting |
| 2. 8 | Extended menu | Extended menu for dealers setup to match features on sprayer |
| L | 1 | |

| 3 | | | Calibration | Basic calibration,e.g. speed, boom, regulation constant, tank and track |
|------|----|---------|-------------------------|--|
| 3. 1 | | | Speed calibration | Sprayer, tractor, Alpha or radar speed input. Calibration of selected sensor |
| | 3. | . 1. 1 | Sprayer speed | Speed sensor mounted on trailed sprayer Connected to armature junction box |
| | | 3.1.1.1 | Sprayer speed constant | Shows and permits change to the constant, Pulses Per Unit (meter / feet) |
| | | 3.1.1.2 | Sprayer speed practical | Preferred method. Do in field with spray tank half full for most accurate result |

| 3. 1. 1. 2. 1 Sprayer practical | Measure up a distance more than 70 meters or 200 feet. Then drive distance |
|-------------------------------------|--|
| 3. 1. 1. 2.2 | Now key in the exact distance, measured by a measuring tape |
| 3. 1. 1. 2.3 | This is the new constant (pulses per meter or feet) |
| 3. 1. 2 Tractor Alpha speed | Alpha, or sensor located on tractor Sensor cable connected to Terminal |
| 3. 1. 2. 1 Tractor speed constant | |
| 3. 1. 2. 2 Tractor practical | Preferred method. Do in field with spray tank half full for most accurate result |
| 3. 1. 3 Radar speed | Choose if radar speed sensor is used |
| 3. 1. 3. 1 Radar speed constant | Shows and permits change to the constant, Pulses Per Unit (meter / feet) |
| 3. 1. 3. 2 Radar practical | Preferred method. Do in field with tank half full for most accurate result |
| 3. 1. 3. 2. 1 | Measure up a distance more than 70 meters or 200 feet. Then drive distance |
| 3. 1. 3. 2. 2 | Now key in the exact distance, measured by a measuring tape |
| 3. 1. 3. 2. 3 | This is the new constant (pulses per meter or feet) |
| 3. 2 Flow calibration | Flow sensor calibration. Theoretical (PPU), Nozzle Tank method PrimeFlow |
| 3. 2. 1 PPU theory method | EU: dia/ca PPU: Ø13/120, Ø20/60, Ø36/17 US: dia/ca PPU: Ø13/485, Ø20/225, Ø36/60 |
| 3. 2. 2 Nozzle method | Practical flow calibration, by checking the actual nozzle output per minute |
| 3. 2. 2. 1 Nozzle method | measure the flow per minute from a number of nozzles. Press Enter. |
| 3. 2. 2. 2 Nozzle method | Key in the averaged actual flow value and press Enter |
| 3. 2. 2. 3 Nozzle method | This is the PPU constant from the volume previously just measured |
| 3. 2. 2. 4 Open all sections | |
| 3. 2. 2. 5 Close end nozzles, Bi-je | nozzles |
| 3. 2. 3 Tank method | Practical flow calibration done by emptying over half the tank |
| 3. 2. 3. 1 Tank method | The sprayed amount is counted up when the sections are opened |
| 3. 2. 3. 2 Tank method | Press Enter. The shown volume is adjusted to match the actual volume |
| 3. 3 Boom setup | Boom width, number of sections and number of nozzles for each section |
| 3. 3. 1 Width | The total spray boom width. Include end nozzles if fitted |
| 3. 3. 2 Number of sections | The number of spray boom sections. Key in, then press Enter |
| 3. 3. 3 Nozzles / sections | To set up no. of nozzles per section. Screens for each section will appear |
| 3. 3. 3. 01 Section 1 | Use arrow keys or numeric keys, then press Enter to set up section 1 |
| 3. 3. 3. 02 Section 2 | Use arrow keys or numeric keys, then press Enter to set up section 2 |
| 3. 3. 3. 03 Section 3 | Use arrow keys or numeric keys, then press Enter to set up section 3 |
| 3. 3. 3. 04 Section 4 | Use arrow keys or numeric keys, then press Enter to set up section 4 |
| 3. 3. 3. 05 Section 5 | Use arrow keys or numeric keys, then press Enter to set up section 5 |
| 3. 3. 3. 00 Section 7 | Use arrow keys of numeric keys, then press Enter to set up section 6 |
| 3. 5. 5. 07 Section 9 | Use arrow keys or numeric keys, then press Enter to set up section 7 |
| 3. 3. 3. 00 Section 0 | Use arrow keys or numeric keys, then press Enter to set up section 8 |
| 3. 3. 3. 09 Section 9 | Use arrow keys or numeric keys, then press Enter to set up section 9 |
| 3 3 3 11 Section 11 | Use arrow keys or numeric keys, then press Enter to set up section 10 |
| 3 3 3 12 Section 12 | Use arrow keys or numeric keys, then press Enter to set up section 12 |
| 3 3 3 13 Section 13 | Use arrow keys or numeric keys, then press Enter to set up section 12 |
| 3 3 4 End nozzles and Bi-iet | Discrete and the set of the set o |
| 3. 3. 4. 1 None | If no end nozzles or Bi-iet nozzles are fitted, select this |
| 3. 3. 4. 2 End nozzles fitted | Select if end nozzles are fitted |
| 3. 3. 4. 2. 1 End nozzles | Key in 'n', number of regular nozzles equivalent to the end nozzle coverage |
| 3. 3. 4. 3 Bi-jet fitted | Select if Bi-jet nozzles are fitted |
| 3. 3. 4. 3. 1 Bi-jet end nozzles | |
| 3. 3. 5 Length hitch to axle fo | ASC Length from hitch to axle on sprayer for AutoSectionControl for ISObus |
| 3. 3. 6 Length axle to boom for | ASC Length from axle on sprayer to boom for AutoSectionControl for ISObus |
| 3. 4 Regulation user setup | Setup of pressure filter, nozzle, ASC default |
| 3. 4. 1 Flow sensor restriction | Flow to obtain 1 bar (15 psi) pressure drop over pressure filter and flow sensor |
| 3. 4. 2 Simulated speed value | Type in speed for priming at stand still and when both flow and pressure are defect |
| 3. 4. 3 Nozzle size flow at 3 ba | (45 psi) 0075Pink = 0.3 02Yellow = 0.8 04Red = 1.6 08White = 3.2 l/min |
| 3. 4. 4 Dual line second nozzl | 0075Pink = 0.3 02Yellow = 0.8 04Red = 1.6 08White = 3.2 l/min |
| 3. 4. 5 Type of nozzle | Select Regular or QuintaStream nozzle |
| 3. 4. 5. 1 Regular nozzle | Flat fan, Low drift, Minidrift |
| 3. 4. 5. 2 QuintaStream | QuintaStream fertilizer nozzle |
| 3. 4. 6 Regulation parameter | Code for special machines or applications, consult your dealer |

| 3. 5 | Tank gauge calibration | Setup density of chemical or fertilizer. Calibration for tank size and shape |
|------------------|--------------------------------|--|
| 3. 5. 1 | Adjustment of specific gravity | Enter weight of liquid fertilizer divided by weight of water (e.g. 1.10 to 1.30) |
| 3. 5. 2 | Calibration of Tank gauge | Calibrate if factory calibration is not adequate. Disable SafeTrack |
| 3.5.2.1 | Water level | Fill up the tank to the max level, then press Enter |
| 3.5.2.2 | Water level | Level the sprayer, then press Enter |
| 3.5.2.3 | Water level | Empty sprayer through main flow meter at boom. Computer will register flow |
| 3.5.2.4 | Water level | Key in true volume from flowmeter. Computer will calculate table |
| 3. 5. 3 | Select factory calibration | Select preloaded factory calibration for Hardi [®] tanks or custom calibration |
| 3.5.3.1 | Custom calibration of gauge | Tank gauge table from custom Calibration |
| 3, 5, 3, 2 | CME 3300 factory calibration | Factory tank gauge table for CME 3300 |
| 3, 5, 3, 3 | CME 4500 factory calibration | Factory tank gauge table for CME 4500 |
| 3. 5. 3. 4 | CME 7000 factory calibration | Factory tank gauge table for CME 7000 |
| 3. 5. 3. 5 | CME 9000 factory calibration | Factory tank gauge table for CME 9000 AUS |
| 3. 5. 3. 6 | Alpha 2500 factory calibration | Factory tank gauge table for Alpha 2500 |
| 3 5 3 7 | Alpha 3500 factory calibration | Factory tank gauge table for Alpha 3500 |
| 3 5 3 8 | Alpha 4100 factory calibration | Eactory tank gauge table for Alpha 4100 |
| 3 5 3 9 | Alpha 3000 factory calibration | Eactory tank gauge table for Alpha 3000 |
| 3 5 3 10 | CME 5x00 factory calibration | Eactory tank gauge table for CME 5000 ALIS |
| 3 5 3 11 | CME 5x00 factory calibration | Eactory tank gauge table for CME 2x00 AUS |
| 2 5 2 12 | Saritor 4000 factory cal | Eactory tank gauge table for Caritor 4000 |
| 2 5 2 12 | Saritor 5000 factory cal | Eactory tank gauge table for Saritor 5000 |
| 2.5.2.14 | Nevigeter 2000 festery cel | Factory tank gauge table for Navigetor 2000 |
| 3. 5. 3. 14 | Navigator 3000 factory cal | Factory tank gauge table for Navigator 3000 |
| 3. 5. 3. 15 | | Factory tank gauge table for CME 5500 FULLS |
| 3. 5. 3. 10 | CME 10 000 fe sterne sel | Factory tank gauge table for CME 5000 E0 05 |
| 3. 5. 3. 17 | CME 10,000 factory cal | Factory tank gauge table for CME 10,000 |
| 3. 5. 3. 18 | Navigator 5000 factory cal | Factory tank gauge table for Navigator 5000 |
| 3. 5. 3. 19 | Navigator 6000 factory cal | Factory tank gauge table for Navigator 6000 |
| 3. 5. 3. 20 | Presidio 2700 factory cal | Factory tank gauge table for Presidio 2700 EU US |
| 3. 5. 4 | Offset at empty Main lank | Actual frequency. Accept if empty. Or key in recorded empty-frequency |
| 3. 5. 4. 1 | TankGauge Offset, | |
| 3.6 | Track calibration | Track width, tractor drawbar length, damping, alignment, sensitivity set up |
| 3. 6. 1 | | Track width of the sprayer wheels measured center to center |
| 3. 0. 2 | | Inactor drawbar length is length from tractor fear axie to pin-bolt |
| 3. 0. 3 | Dead zone for regulation | Increase for high speed, Decrease for high accuracy |
| 3. 6. 4 | Damping of hydraulics | Increase for smooth drive and high speed. Decrease for high accuracy |
| 3. 6. 5 | Align offset + right - left | Alignment of sprayer. Positive value moves sprayer right, negative left |
| 3. 6. 6 | Calibrate sensitivity | Adjustment of track sensitivity in relation to the tractor hydraulics |
| 3. 6. 6. 01 | Sensitivity tractor hydraulic | Press ESC to abort. Press Enter to start calibration of offset and gain |
| 3. 6. 6. 02 | Finding offset right side | Press hold 'steer to right' button. Computer will activate valve to find offset |
| 3. 6. 6. 03 | Offset right side is Ok | |
| 3. 6. 6. 04 | Finding offset right failed | Press Enter to return to Track calibration menu |
| 3. 6. 6. 05 | Finding offset left side | Press hold 'steer to left' button. Computer will activate valve to find offset |
| 3. 6. 6. 06 | Offset left side is Ok | |
| 3. 6. 6. 07 | Finding offset left failed | Press Enter to return to Track calibration menu |
| 3. 6. 6. 08 | Finding gain right side | Press hold 'steer to right' button. Computer will activate valve and find gain |
| 3.6.6.09 | Gain right side is Ok | |
| 3. 6. 6. 10 | Find gain right side failed | Press Enter to return to Track calibration menu |
| 3.6.6.11 | Finding gain left side | Press hold 'steer to left' button. Computer will activate valve and find gain |
| 3.6.6.12 | Gain left side is Ok | Calibration is OK. Press Enter to return to Track calibration menu |
| 3.6.6.13 | Finding gain left side failed | Press Enter to return to Track calibration menu |
| 3. 6. 6. 14 | Stop driving | Stop driving |
| 3. 6. 6. 15 | Switch to auto | Switch to auto track |
| | | |
| | | |
| 4 | Toolbox | Helpful tools e.g. measure distance and area, service intervals, test etc |
| 4 4. 1 | Toolbox Measure | Helpful tools e.g. measure distance and area, service intervals, test etc To measure distance and area. Setup working width |

Measure stopped. Press C to clear, Enter to start and ESC to exit

4. 1. 1 4. 1. 1. 1

Measure Distance

| 4.1.1.2 | Measure Distance | Measure started. Press Enter to stop and ESC to exit |
|------------------|-------------------------------|--|
| 4. 1. 2 | Measure Area | If the implement width is Entered, area can also be measured |
| 4. 1. 3 | Setup working width | Key in the implement working width |
| 4. 1. 4 | Stop-watch | The clock can be used as a stop watch |
| 4.1.4.1 | Stopwatch: Not active | Press C to clear. Press Enter to start, Esc to exit |
| 4.1.4.2 | Stopwatch: Active | Press Enter to stop and edit. Press Esc to exit. Stopwatch will continue |
| 4. 1. 5 | Alarm clock | The clock can be set as an alarm clock |
| 4.1.5.1 | Alarm clock: Not active | Key in time. Press C to clear. Press Enter to start. Press ESC to exit. |
| 4.1.5.2 | Alarm clock: Active | Press Enter to stop and edit. Press Esc to exit. Alarm clock will continue |
| 4. 2 | Service interval: Hours until | Work hours remaining for each part until next service is recommended |
| 4. 2. 1 | 10 hrs Check filters | |
| 4. 2. 2 | 50 hrs Grease boom | |
| 4. 2. 3 | 250 hrs Grease center | |
| 4. 2. 4 | Misc. service | |
| 4. 2. 5 | 10 hrs Check nozzles | |
| 4. 3 | Service interval reset | Reset timer counter when service has been carried out |
| 4. 3. 1 | Check filters reset | Press Enter to reset hour counter, ESC to leave unchanged |
| 4. 3. 2 | Grease boom reset | Press Enter to reset hour counter, ESC to leave unchanged |
| 4. 3. 3 | Grease track and center | Press Enter to reset hour counter, ESC to leave unchanged |
| 4. 3. 4 | Miscellaneous service | Press Enter to reset hour counter, ESC to leave unchanged |
| 4. 3. 5 | Check nozzles | Press Enter to reset hour counter, ESC to leave unchanged |
| 4. 4 | Reserved | RR |
| 4. 5 | Test of sensors | Test screens for buttons, sensor readings PrimeFlow status Valve friction |
| 4. 5. 1 | Flow Speed Optional sensors | Activate function to monitor sensor (e.g. drive forwards, start flow) |
| 4.5.1.1 | Pressure | |
| 4.5.1.2 | Fan Speed | |
| 4.5.1.3 | Tank gauge | |
| 4.5.1.4 | Boom sensor | |
| 4.5.1.5 | Pressure regulation feedback | |
| 4.5.1.6 | Flow | |
| 4.5.1.7 | Speed | |
| 4. 5. 2 | Active keys | Push key to see if a count is registered. If yes, the key or switch function is OK |
| 4.5.2.1 | Keys on Terminal | |
| 4.5.2.2 | Keys on SetBox | |
| 4.5.2.3 | Keys on Grip | |
| 4.5.2.4 | Keys on FluidBox | |
| 4. 5. 3 | PrimeFlow test | PrimeFlow test for nozzles and PrimeFlow computers on boom |
| 4. 5. 3.1 to 125 | PrimeFlow computer status | Press Arrow DOWN to see next SMCU Arrow UP to see previous |
| 4. 5. 3. 1.1 | Total SMCU's | |
| 4. 5. 3. 1.2 | Total nozzles | |
| 4. 5. 3. 1.3 | This SMCU position | |
| 4. 5. 3. 1.4 | Nozzle order | |
| 4. 5. 3. 1.5 | Nozzle no short cab. | |
| 4. 5. 3. 1.6 | Nozzle medium cable | |
| 4. 5. 3. 1.7 | Nozzle no long cable | |
| 4. 5. 3. 1.8 | Count of data error | |
| 4. 5. 3. 1.9 | Count of power error | |
| 4. 5. 4 | Input test | See computer readings of sensors Frequency, switch, analog inputs |
| 4.5.4.1 | Frequency 1 Speed, Flow | Test of frequency input sensors: Speed, Flow, Tank gauge, Fan |
| 4. 5. 4. 1. 1 | Speed | |
| 4. 5. 4. 1.2 | Flow to sections | |
| 4. 5. 4. 1.3 | Flow from rinse tank | |
| 4. 5. 4. 1.4 | FlexCap pump RPM | |
| 4. 5. 4. 1. 5 | Tank gauge | |
| 4. 5. 4. 1.6 | Wind Speed | |
| 4. 5. 4. 1. 7 | Fan speed | |
| 4. 5. 4. 1.8 | PTO pump RPM | |

| 4. 5. 4. 1. 9 Speed to termina | al | |
|---------------------------------|-----------------|--|
| 4. 5. 4. 2 Freq. 2 input Extr | ra Test | t of frequency 2 sensors: Extra Regulation, agitation valve |
| 4. 5. 4. 2. 1 Regulation valve | | |
| 4. 5. 4. 2. 2 Agitation valve | | |
| 4. 5. 4. 2. 3 Boom folded Left | t | |
| 4. 5. 4. 2. 4 Boom folded Rig | ht | |
| 4. 5. 4. 3 Switch on/off inp | outs Test | t Switch inputs function 0 equals connected, 1 equals open |
| 4. 5. 4. 3. 1 Pendulum lock | | |
| 4. 5. 4. 3. 2 Ladder up | | |
| 4. 5. 4. 3. 3 HY interface erro | r | |
| 4. 5. 4. 3. 4 SmartValve switc | :h | |
| 4. 5. 4. 3. 5 Main tank float | | |
| 4. 5. 4. 3. 6 Rinse tank float | | |
| 4. 5. 4. 3. 7 12V relay DAH bo | хс | |
| 4. 5. 4. 3. 8 Foot Switch term | ninal (HC | 6500 only) |
| 4. 5. 4. 4 Analog 1 inputs 8 | Boom Test | t Analog 1 sensors on boom: Slant, Height, Tilt, Foam, TWIN |
| 4. 5. 4. 4. 1 Slant | | |
| 4. 5. 4. 4. 2 Boom height | | |
| 4. 5. 4. 4. 3 PF bus + | | |
| 4. 5. 4. 4. 4 PF bus - | | |
| 4. 5. 4. 4. 5 Foam blob distar | nce | |
| 4. 5. 4. 4. 6 TWIN angle | | |
| 4. 5. 4. 4. 7 TWIN fan r/min | | |
| 4. 5. 4. 4. 8 Agitation angle | | |
| 4. 5. 4. 4. 9 Reg. valve angle | | |
| 4. 5. 4. 5 Analog 2 inputs I | Extra Test | t Analog 2 sensors: Electric smart valves, extra |
| 4. 5. 4. 5. 1 Distance center | | |
| 4. 5. 4. 5. 2 PrimeFlow volt le | eft | |
| 4. 5. 4. 5. 3 PrimeFlow volt ri | ght | |
| 4. 5. 4. 5. 4 Dynamic center | pos. | |
| 4. 5. 4. 5. 5 Lock sensor | | |
| 4. 5. 4. 5. 6 Pendulum lock | atar | |
| 4. 5. 4. 5. 7 Suction SV potent | or | |
| | er | |
| 4 5 4 6 Track sensor test | Act | ual sensor signals Inder 0.5 volt means not connected |
| 4 5 4 6 1 Front sensor | | |
| 4 5 4 6 2 Front sensor | | |
| 4 5 4 6 3 Rear sensor | | |
| 4, 5, 4, 6, 4 Rear sensor | | |
| 4. 5. 4. 6. 5 Boom sensor 1 | | |
| 4. 5. 4. 6. 6 Boom sensor 1 | | |
| 4. 5. 4. 6. 7 Boom sensor 2 | | |
| 4. 5. 4. 6. 8 Lock sensor | | |
| 4. 5. 4. 6. 9 Lock sensor | | |
| 4. 5. 4. 7 SafeTrack sensitiv | vity view Hig | her offset higher current to open Higher gain mean more oil at current |
| 4. 5. 4. 7. 1 Left offset value | | |
| 4. 5. 4. 7.2 Right offset value | 2 | |
| 4. 5. 4. 7.3 Left gain factor | | |
| 4. 5. 4. 7. 4 Right gain factor | | |
| 4. 5. 4. 8 Twin boom fold s | sensors Stat | tus=1 is 5 volt or not connected Under 0.5 volt is not connected |
| 4. 5. 4. 8. 1 Louter boom tra | insp. | |
| 4. 5. 4. 8. 2 Louter boom sp | ray | |
| 4. 5. 4. 8. 3 R outer boom tra | insp. | |
| 4. 5. 4. 8. 4 R outer boom sp | ray | |
| 4. 5. 4. 9 Speed, Pumps RF | 'M mounting Dut | y cycle indicate distance 70% = too close 20%= too far away |
| 4. 5. 4. 9.1 Speed | | |

| | 4. 5. 4. 9.2 Speed duty cycle 1 | |
|-----|-------------------------------------|--|
| | 4. 5. 4. 9. 3 Speed duty cycle 2 | |
| | 4. 5. 4. 9. 4 Speed max duty cycle | |
| | 4. 5. 4. 9. 5 Speed min duty cycle | |
| | 4. 5. 4. 9 6 PTO pump RPM | |
| | 4. 5. 4. 9.7 PTO pump duty cycle | |
| | 4. 5. 4. 9. 8 FlexCap pump freq. | |
| | 4. 5. 4. 9. 9 FlexCap duty cycle | |
| 4.5 | 5. 5 Fluid and valve test | Test of regulation and electric valves |
| 4 | 4. 5. 5. 1 Show SmartValve friction | Turn time increase with friction. Limit 900 msec to 1300msec. C to clear |
| | 4. 5. 5. 1. 1 Suct valve avr CW | |
| | 4. 5. 5. 1. 2 Suct valve avr CCW | |
| | 4. 5. 5. 1. 3 PressurValve avr CW | |
| | 4. 5. 5. 1. 4 PressurValve avr CCW | |
| | 4. 5. 5. 1. 5 FastEValve avr CW | |
| | 4. 5. 5. 1. 6 FastEValve avr CCW | |
| 4 | 4. 5. 5. 2 Regulation sensors | Details for regulation sensor inputs Boom pressure Flow Pump RPM |
| ΙF | 4. 5. 5. 2. 1 Boom pressure | and a state of the second beaution of the sec |
| | 4. 5. 5. 2. 2 Boom flow sensor | |
| | 4. 5. 5. 2. 3 Pump RPM | |
| | 4. 5. 5. 2. 4 FlexCapacity RPM | |
| | 4. 5. 5. 2. 5 Reg. valve sensor | |
| | 4. 5. 5. 2. 6 Agt. valve sensor | |
| | 4. 5. 5. 2. 7 Reserved | |
| | 4. 5. 5. 2. 8 Reserved | |
| | 4. 5. 5. 2. 9 Regulator state | |
| 4 | 4. 5. 5. 3 Flow calculations | Check flow calculations are realistic with current settings of sprayer |
| | 4. 5. 5. 3. 1 Boom pressure | |
| | 4. 5. 5. 3. 2 Agitation calc press | |
| | 4. 5. 5. 3. 3 Pump calc flow | |
| | 4. 5. 5. 3. 4 Agit valve calc flow | |
| | 4. 5. 5. 3. 5 Reg valve calc flow | |
| | 4. 5. 5. 3. 6 Boom flow sensor | |
| | 4. 5. 5. 3. 7 Nozzle SizeQ 3bar A | |
| | 4. 5. 5. 3. 8 Nozzle SizeQ 3bar B | |
| | 4. 5. 5. 3. 9 Nozzle SizeQ 3bar AB | |
| 4 | 4. 5. 5. 4 RS232(COM1) serial test | Inactive, No connection, No data, Wrong CRC, Unsupported command, Valid data |
| | 4. 5. 5. 4.1 COM1 near bracket | |
| | 4. 5. 5. 4. 2 Signal detec on port | |
| | 4. 5. 5. 4. 3 Valid telegram | |
| | 4. 5. 5. 4. 4 Wrong baud rate | |
| | 4. 5. 5. 4. 5 Overrun error | |
| | 4. 5. 5. 4. 6 CRC err acc. to spec | |
| | 4. 5. 5. 4.7 Unsupported telegram | |
| 4 | 4. 5. 5. 5 RS232(COM2) serial test | Inactive, No connection, No data, Wrong CRC, Unsupported command, Valid data |
| | 4. 5. 5. 5. 1 COM2 near edge | |
| | 4. 5. 5. 5. 2 Signal detec on port | |
| | 4. 5. 5. 5. 3 Valid telegram | |
| | 4. 5. 5. 5. 4 Wrong baud rate | |
| | 4. 5. 5. 5. 5 Overrun error | |
| | 4. 5. 5. 5. 6 CRC err acc. to spec | |
| | 4. 5. 5. 5. 7 Unsupported telegram | |
| 4 | 4. 5. 5. 6 Extra reg. diagnose | Saritor hydraulic valve |
| | 4. 5. 5. 6. 1 Hydr. valve offset | |
| | 4. 5. 5. 6. 2 Hydr. valve slope | |
| | 4. 5. 5. 6. 3 Hydr. valve hysteres | |
| 4 | 4. 5. 5. 7 EVC reg. diagnose | EVC regulation diagnose |
| 4. 5. 5. 7. 1 | Boom flow sensor | |
|-----------------------|--------------------------------|--|
| 4 5 5 7 2 | EVC change deviation | |
| 4 5 5 7 3 | Reg V end to end T | |
| 4 5 5 8 | lobCom voltage monitor | 12 V battery 5 V sensor may min hold |
| 4 5 5 8 1 | 12 V battery max | |
| 4 5 5 9 2 | 12 V battery min | |
| 4. 5. 5. 6. 2 | | |
| 4. 5. 5. 8. 5 | 5 V battery max | |
| 4. 5. 5. 8. 3 | 5 V battery min | |
| 4. 5. 6 | PrimeFlow SMCU status | See nozzle position, nozzle order, counts of data error power error |
| 4.5.6.1 | First nozzle for SMCU | Position of first nozzle on boom counted from left |
| 4.5.6.2 | SMCU 2 or 3 nozzle | Produced or reprogrammed. SMCU with 3 cables could be changed to 2 nozzles |
| 4.5.6.3 | Nozzle order | Show when connected in normal order Short Medium Long from left - |
| 4.5.6.4 | Count of data error | Times were SMCU did not respond to alive telegram. C to reset counters |
| 4.5.6.5 | Count of power error | Times were SMCU shot down due to low voltage. C to reset counters |
| 4.5.6.6 | SMCU version | View SMCU versions |
| 4. 5. 7 | PrimeFlow motor status | |
| 4.5.7.1 | Motor 1-90 disconnect | Motor or connector disconnected Press C to reset |
| 4.5.7.2 | Motor 91-180 disconnect | Motor or connector disconnected Press C to reset |
| 4.5.7.3 | Motor 1-90 shorted | Motor or connector short circuited Press C to reset |
| 4.5.7.4 | Motor 91-180 shorted | Motor or connector short circuited Press C to reset |
| 4.5.7.5 | Motor 1-90 blocked | Motor connection ok, but motor cannot move. Press C to reset |
| 4.5.7.6 | Motor 91-180 blocked | Motor connection ok, but motor cannot move. Press C to reset |
| 4. 6 | Speed simulation | Key in speed value. To disable simulation key in 0 or power off |
| 4. 7 | Emergency | |
| 4. 7. 1 | Track align | Emergency only. Align sprayer and fold boom, in case a sensor is defect |
| 4. 7. 1. 1 | Front sensor | |
| 4. 7. 1. 2 | Front sensor | |
| 4. 7. 1. 3 | Rear sensor | |
| 4 7 1 4 | Rear sensor | |
| 4 7 1 5 | Boom sensor 1 | |
| 4 7 1 6 | Boom sensor 1 | |
| 4 7 1 7 | Lock sensor | |
| 4 7 1 8 | Lock sensor | |
| 4 7 1 9 | SafeTrack mode | |
| 4 7 2 | Boom fold | Emergency only Manual lock and fold boom, in case a sensor is defect |
| 1, 7, 2 1, 7, 2, 1 | | Energency only. Mandahoek and fold boom, in case a sensor is deleter |
| 4.7.2.1 | Dynamic center pos. | |
| 4.7.2.2 | Bendulum lock | |
| 4. 7. 2. 3 | | |
| 4. 7. 2. 4 | | |
| 4. 7. 2. 5 | Boom sensor I | |
| 4. /. 2. 6 | boom sensor i | |
| 4. /. 2. 7 | Boom neight status | |
| 4. /. 2. 8 | Boom height | |
| 4. 7. 2. 9 | Boom hydraulics | |
| 4. 8 | Computer CAN status | Menus for a diagnostic system check. Counter of errors. SW HW versions |
| 4. 8. 1 | Operating status all computer | Computer detail screens show details in case of faults |
| 4.8.1.1 | Terminal HC 6500 | |
| 4.8.1.2 | JobCom HC 6100 | |
| 4.8.1.3 | Grip HC 6300 | |
| 4.8.1.4 | SetBox HC 6400 | |
| 4.8.1.5 | FluidBox HC 6200 | |
| 4. 8. 2 | Software versions all computer | Computer detail screens show details in case of faults |
| 4.8.2.1 | JobCom HC 6100 | |
| 4.8.2.2 | Grip HC 6300 | |
| 4.8.2.3 | SetBox HC 6400 | |
| 4.8.2.4 | FluidBox HC 6200 | |
| 4. 8. 3 | Hardware versions all computer | Computer detail screens show details in case of faults |

3 - Description

| | 4.8.3.1 | JobCom HC 6100 | |
|----|---------|------------------------------|---|
| | 4.8.3.2 | Grip HC 6300 | |
| | 4.8.3.3 | SetBox HC 6400 | |
| | 4.8.3.4 | FluidBox HC 6200 | |
| 4 | . 8. 4 | Work status Terminal HC 6500 | Faults occurred Press C key to reset counters |
| | 4.8.4.1 | Terminal HC 6500 | |
| | 4.8.4.2 | JobCom HC 6100 | |
| | 4.8.4.3 | Grip HC 6300 | |
| | 4.8.4.4 | SetBox HC 6400 | |
| | 4.8.4.5 | FluidBox HC 6200 | |
| | 4.8.4.6 | Internal HW error | |
| 4 | . 8. 5 | Work status JobCom HC 6100 | Faults occurred Press C key to reset counters |
| | 4.8.5.1 | CANbus short circuit | |
| | 4.8.5.2 | CAN bus open circuit | |
| | 4.8.5.3 | | |
| | 4.8.5.4 | Watchdog reset | |
| | 4.8.5.5 | Cannot logon | |
| | 4.8.5.6 | Data missing | |
| | 4.8.5.7 | Receive data invalid | |
| | 4.8.5.8 | CAN bus overflow | |
| | 4.8.5.9 | Max. used stack | |
| 4. | . 8. 6 | Work status Grip HC 6300 | Faults occurred Press C key to reset counters |
| 4. | . 8. 7 | Work status SetBox HC 6400 | Faults occurred Press C key to reset counters |
| 4. | . 8. 8 | Work status FluidBox HC 6200 | Faults occurred Press C key to reset counters |

| 5 | |
|---|--|
| - | |

| | Logbook | Data records of registers or configuration for print or dump |
|---|------------------------------|--|
| . 1 | Print | Register and configuration can be printed to the 12 volt printer |
| 5. 1. 1 | Print single register | A specific register is selected for a Print |
| 5.1.1.1 | | Key in number of specific register to print. Press Enter to start printing |
| 5.1.1.2 | | Bytes printed at 9600 8-N-1 baud. Press ESC to cancel |
| 5. 1. 2 | Print all registers | Registers in use will be printed. Print starts upon key press on Enter |
| 5. 1. 3 | Print configuration | Records all system parameters. Print starts upon key press on Enter |
| 5. 1. 4 | Print PrimeFlow status | Print status for all computer. Print starts upon key press on Enter |
| 5. 1. 4. 1 Printing. Press ESC to abort | | Printing. Press ESC to abort |
| 5. 1. 5 | Print PrimeFlow motor status | Print status for all motors |
| 5.1.5.1 | | Printing. Press ESC to abort |
| . 2 | Data dump | Register and configuration can be dumped to a PC via e.g. Hyper Terminal |
| 5. 2. 1 | Data dump of raw data | Transmits data from all 99 registers in comma-separated file for Excel |
| 5. 2. 2 | Hyperterminal service report | Transmits to PC at high speed Configuration ErrorLog Track PrimeFlow |

Tractor installation

Installation of control unit brackets

Find a suitable place in the tractor's cabin to secure the control units from movement. Best recommended placement is to the right of the driver seat.



The supplied tractor pillar bracket (A) has a hole spacing of 3.9 in. (100 mm) and 4.7 in. (120 mm) and will fit most tractors. Threaded mounting holes may be hidden behind front corner cover.



ATTENTION! Check tractor instructions manual for information regarding attachment points.

Three tubes (B) are supplied. One, two or all 3 may be used. They can be bent and shortened. A spacer (C) is also supplied to allow further attachment possibilities. Find the best solution for your tractor or vehicle.

Tube (B) plate is staggered so all boxes will line up if correctly oriented.

The recommended setup is to place the spacer (C) between the two tubes (B) used for the controllers and the 3rd tube (B) as shown in the picture, so it can be mounted in the bracket (A).



Printer

If the 12 Volt printer is fitted, the supplied tube can be utilized to fit the printer on the Controller brackets.

ATTENTION! The Controller should be protected from moisture and should be removed when not in use, if the tractor does not have a cabin.

Speed transducer for sprayer

The speed transducer is located at the inside of the sprayer's right wheel. It is an inductive type that requires a metallic protrusion to pass by it to trigger a signal. A speed ring is used to trigger the transducer. It should be adjusted so the transducer is placed in the center of the holes in the speed ring (vertical direction). Recommended distance between protrusion and transducer (A) is 1/8" to 1/4" (3 to 6 mm). Check throughout the entire circumference. Correct adjustment is indicated by a constant blinking from the transducer when the wheel rotates.



How to set clock

If time or date is out of adjustment, it can be corrected as follows.

ATTENTION! This must be done at very first start-up, when prompted. If no prompt, the HARDI® dealer may have done this.

- 1. Press {Enter} on ISOBUS Terminal.
- 2. Press {down} arrow to menu [2 Setup]. Press {Enter}.
- 3. Press {down} arrow to menu [2.4 Set clock]. Press {Enter}.
- 4. Press {Enter} to enter first submenu, menu [2.4.1 Time format (12 or 24 hour)].
- 5. By using {up} or {down} arrows you can choose between:

Menu [2.4.1.1 12 hour format].

Menu [2.4.1.2 24 hour format].

- 6. Press {Enter} to select format and return to previous menu by pressing {ESC}.
- 7. Press {down} arrow to menu [2.4.2 Set time].
- 8. Press {Enter} and select minutes or hours, then enter value with numeric keys.
- 9. Press the check mark to confirm.
- 10. Press {down} arrow to menu [2.4.3 Set date and month].
- 11. Press {Enter} and select day or month, then enter value with numeric keys.
- 12. Press the check mark to confirm.
- 13. Press {down} arrow to menu [2.4.4 Set year].
- 14. Press {Enter} and select year, then enter value with numeric keys.
- 15. Press the check mark to confirm.
- 16. Press {ESC} to exit menu.

Initial settings

System start-up

When turned ON:

- The system initiates itself.
- If the system is put into operation for the very first time it will prompt for date and time. Set clock to enable register. Refer to "How to set clock" on page 4.2 for details on setting of clock.

Display readout

It is possible to freely choose which functions are shown in the 4 different boxes (A, B, C and D) of the display.



ATTENTION! Read more about difference between HC 6500 and ISOBUS in "Menu 2.1 Display readout" on page 6.1.

Readout selection

- 1. Go to menu [2.1 Display readout].
- 2. Use {up} or {down} arrows to choose which of following boxes you want the data shown and press {Enter} to confirm.

2.1.1 Show upper middle (A)

2.1.2 Show upper right (B)

2.1.3 Show lower middle (C)

2.1.4 Show lower right (D)

- 3. Choose a submenu e.g. menu [2.1.1.04 Work rate]. Press {Enter} to confirm.
- 4. Press {ESC} to leave menu.

ATTENTION! For a full list of possible readouts, please refer to menu 2.1.1, menu 2.1.2, menu 2.1.3 and menu 2.1.4 in "Full menu structure" on page 3.15.

ESC key for ISOBUS terminals

Menu 2.1.5 changes how the ESC key is operated.

- Menu 2.1.5.1 "Show ESC as softkey": Select this menu if there is no ESC button on the ISOBUS terminal.
- Menu 2.1.5.2 "Do not show ESC as softkey": Select this menu if the ISOBUS terminal has a physical ESC button.





ATTENTION! If the ESC softkey is removed on a display without a physical ESC button, navigation will become impossible and will require service to fix. Only select menu 2.1.5.2 if a physical ESC button exists.



Working in the field

Set up before spray job

The following steps are to be taken to set up the sprayer before beginning a spray job.

1. Set the volume rate for the present spray job.



2. Select the nozzle type to be used for normal spray or fertilizer spraying.

| 3.4.5. 1 | ESC |
|-----------|----------|
| | 1 |
| | , L |
| | ¥ |
| | |
| | |
| linidrift | |
| | 3.4.5. 1 |

3. Adjust specific gravity when changing between a normal spray job and fertilizer spraying.



4. If the sprayer is not equipped with Tank Gauge, then type in the contents filled into the main tank.



5. Select register for the present spray job (if desired).



6. For SafeTrack, the sensitivity of the tractor hydraulic must be calibrated. Follow the instructions written in the bottom of the display.

NOTE! The calibration can only be done with the boom unfolded!



Volume rate

NOTE! When used on an HC 9500 ISOBUS terminal, the volume rate must be set in the HC 9500 software when its graphical field functions are used (not running Virtual Terminal only). In such case, please refer to the HC 9500 instruction book for set up of volume rate.

If running Virtual Terminal only on a HC 9500 the following procedure applies.

The volume rate can be changed by

- Setting the desired rate in the Controller.
- Manually raising or lowering the pressure via the SetBox.
- Pressing {%-up} or {%-down} to apply over or under in a preset percentage, e.g. 10% (the %-icon in the display indicates when this is active).

To read the volume rate

Go to menu [1.1 VOLUME RATE] to read volume rate

To change volume rate

- 1. Go to menu [1.1 VOLUME RATE].
- 2. Change the value. Alternatively clear value by pressing Clear and key in value on the numeric keys.
- 3. Press Enter to confirm.

Manual dosage

To dose in manual mode, use the pressure buttons on the SetBox. The manual mode is indicated by the
symbol at the top of the display.

To go from manual to preset volume rate, press AUTO.



ATTENTION! Under 0.3 mph (0.5 km/h), the Controller will not regulate automatically.

Register readout and selection

Registers are identified with a number. The data is saved when the system is switched off.

- Register 1 to 98 can be used for individual areas.
- Register 99 is a tally of register trips 1 to 98.

To read the totals of all registers:

- 1. Go to menu [1.3 Select register].
- 2. Go to register 99.
- 3. Press Enter to enter the register and read main data.
- 4. Press Enter again to see spray data.
- 5. Press Escape to exit the menu.

To read the data in the active register:

- 1. Go to menu [1.3 Select register].
- 2. Press Enter to enter register and read main data.
- 3. Press Enter again to see spray data.
- 4. Press Escape to exit the menu.

To change the register:

- 1. Go to menu [1.3 Select register].
- 2. Press up or down arrow to change the register.
- 3. Press Enter. If necessary, the register can be reset see below.
- 4. Press Escape to exit the menu.

To reset register:

Press Escape and hold for 5 seconds to reset register. Status diode will blink once, and then blink again to indicate that register has been reset.

Reset of a register can be stopped if the Escape key is released before the status diode is blinks again.

ATTENTION! The active register number is always visible in the right upper corner of the display.

Tank contents

To change the displayed tank contents:

- 1. Go to menu [1.2 Tank contents].
- 2. Set the value.
- 3. Press Enter to confirm.
- 4. The maximum size of the tank is displayed.



ATTENTION! If the sprayer is fitted with Tank gauge, contents readout is automatic.





TWIN Preset

Air volume and air angle can be set in 2 different positions:

- Headwind
- Tail wind

Store manual preset

- 1. Set air volume and air angle for headwind.
- 2. Press a long key press at button for position 1 on the grip to store the present setting.
- 3. Do the same setting for position 2 tailwind.

Store auto preset

TWIN preset can be setup so it will shift automatically from position 1 to position 2 when the main ON/OFF is activated (menu 2.2.5 to 2.2.5.2).

Spraying with DynamicFluid4 pressure regulation

Start up procedure and steps done by the spray driver when beginning a spray job at the headland in the field is described below:

- The controller always starts up in automatic mode.
- If, by some reason, the (+) or (-) has been pressed, the controller enters manual mode. Then press is before beginning any spraying.
- Do not adjust the pressure before and while spraying, as the controller does this automatically.

Regulation valve LED's

The regulation valve is equipped with 4 LED's as indication of valve status:

| LED color | Valve status |
|-----------|--|
| 2 x Red | Out of working range. |
| | The valve disc is out of its normal working range. This does not happen when the regulation valve works correctly. The software will prevent the valve from going out of range, also when manually operated. |
| Yellow | Valve closed. |
| | The valve disc is closed or starts to open, and is within the normal working range. |
| Green | Open and in work range. |
| | The valve disc is open and in its normal working range. This is normal state when spraying. |

Spraying with FlexCapacity pump

On conventional P.T.O. systems, both the P.T.O. pump and the hydraulic FlexCapacity pump deliver constant flow when engaged. Therefore the spray pressure is controlled by the regulation valve when:

- Valves/sections are opened or closed.
- Speed is increased or decreased, etc.

When specific driving conditions or large nozzles makes the regulation valve unable to adjust to correct pressure because of too large or too low flow, i.e. regulation valve is completely open or closed, it requires the FlexCapacity pump to be turned ON/OFF - in general:

- Turn FlexCapacity pump ON when nozzle pressure gets too low. Controller prompts the warning "Increase pump flow".
- Turn FlexCapacity pump OFF when nozzle pressure gets too high. Controller prompts the warning "Reduce pump flow".

Menu 1 Daily settings

Menu 1.1 Volume rate

Volume rate, also called application rate, is the volume of fluid which passes through the nozzles per area unit. Volume rate is measured in gallons per acre.

Setting volume rate is described in "Volume rate" on page 4.5.



Menu 1.2 Tank contents

This menu is to enter tank contents if no tank gauge is fitted.

To set tank contents, see "Tank contents" on page 4.6.



ATTENTION! If the sprayer is fitted with Tank gauge, contents readout is automatic.



Menu 1.3 Select register

- Register 1 to 98 can be used for individual areas.
- Register 99 is a tally of register trips 1 to 98. They are identified with a number. The data is saved when the system is switched off.



ATTENTION! The active register number is always visible in the right upper corner of the display.



5 - Menu 1 Daily settings

Menu 2 Setup

General info

The following menu explanations assume you have mastered the general keystrokes and you can "find your way" to the specific menu. If this is not so, please re-read section "Terminals and boxes" on page 3.3.

Menu 2.1 Display readout

It is possible to freely choose which functions will be shown in the display. The ISOBUS terminals have 6 different boxes (A, B, C, D, E and F). Box A always displays the Volume rate. Boxes B - E display user selected information. Box F displays information selected from the preset keys (Volume sprayed, Distance left, Volume rate, Speed, Tank contents or Area sprayed).

A full list of possible readouts for boxes B - E can be found in the "Full menu structure" on page 3.15.

- A. Volume rate
- B. Selected with menu 2.1.1
- C. Selected with menu 2.1.2
- D. Selected with menu 2.1.3
- E. Selected with menu 2.1.4
- F. Selected with preset keys



ATTENTION! As some readouts need extra sensors, the relevant sensor has to be connected to get a readout.

ESC key for ISOBUS terminals

Menu 2.1.5 changes how the ESC key is operated.

- Menu 2.1.5.1 "Show ESC as softkey": Select this menu if there is no ESC button on the ISOBUS terminal.
- Menu 2.1.5.2 "Do not show ESC as softkey": Select this menu if the ISOBUS terminal has a physical ESC button.





ATTENTION! If the ESC softkey is removed on a display without a physical ESC button, navigation will become impossible and will require service to fix. Only select menu 2.1.5.2 if a physical ESC button exists.

6 - Menu 2 Setup

Menu 2.2 Auto functions

In this menu, several automatic functions can be set up for specific use.

Menu 2.2.1 Main ON/OFF

The Controller can be set to open the main ON/OFF function above a certain speed and close it below the same speed. This allows the user to concentrate on driving.

- If the speed is set at zero, the function is deactivated.
- Suggested speed setting is spraying speed less 20%.

When the Auto ON/OFF function is active while the main ON/OFF switch and boom section switches are on, the boom status symbol will be blue with a bar across whenever the speed is below the preset speed.

This is to indicate that the main ON/OFF switch will automatically open when the sprayer reaches the preset speed.



WARNING! Remember to set the main ON/OFF switch on the grip to OFF before leaving the field, otherwise the main ON/OFF will open under transport.

ATTENTION! When AutoSectionControl is used, the function should be deactivated as the AutoSectionControl will overtake control of the main ON/OFF.

Menu 2.2.2 Foam Marker (optional)

The Controller can be set to operate the HARDI® Foam marker automatically through the main ON/OFF valve. When the main ON/OFF is ON, it will automatically start the Foam marker.

Furthermore, the Foam marker can be set for up and back spraying or race-track (round and round) spraying.

Possible settings are:

| Setting | Activity |
|-------------|---|
| Disable | The marker will only follow the setting of the switch on the SetBox. |
| Same side | The Terminal will automatically activate the same side for race-track spraying. |
| Change side | The Terminal will automatically change side for up and back spraying. |

Menu 2.2.3 DualLine (not used)

Menu 2.2.3.1 Lower pressure level (not used)

Menu 2.2.3.2 Upper pressure level (not used)

Menu 2.2.4 HeadlandAssist setup (not used)

Menu 2.2.5 TWIN preset shift auto/man (TWIN only)

This menu is to select if TWIN preset shifts is automatically at main ON/OFF or manually at key press.

Select the way to use the function in the submenus:

| Menu | Function |
|---------|---|
| 2.2.5.1 | Selects whether manual operation is done at the SetBox or at the buttons behind the grip. |
| 2.2.5.2 | Selects automatic shift every time the main ON/OFF is pressed. |
| 2.2.5.3 | Disables the function. |

Menu 2.3 Variable Rate Application (VRA) / Remote / HARDI® AutoSectionControl

If the volume rate is to come from an external source (e.g. a site specific application map, remote sensor or a GPS system like HARDI® AutoSectionControl), this menu has to be enabled. This is done by selecting one of the submenus:

- Menu 2.3.1 Disable
- Menu 2.3.2 Enable

The 🖉 symbol on the 1st line in the display will be visible. Manual pressure regulation and stepped over/under application is still possible.

Menu 2.4 Set clock

If the Controller prompts for date and time, then set clock to enable register.

This must be done before the Controller is put into operation for the first time, otherwise no start and stop time will be recorded in the registers. Later changes in date and time can be done by following the procedure in "How to set clock" on page 4.2.



ATTENTION! If no prompt, the dealer may already have done this.

In submenus it is possible to select and set:

| Menu | Function | | |
|---------|-----------------------------|----------|--|
| 2.4.1 | Time format (12 or 24 hour) | | |
| 2.4.1.1 | 12 hour format | | |
| 2.4.1.2 | 24 hour format | | |
| 2.4.2 | Set time | | |
| 2.4.3 | Set date and month | | |
| 2.4.4 | Set year | Set year | |

Menu 2.5 Alarms

User selectable alarms can be set with parameters of choices given in the submenus of menu 2.5 - refer to "Full menu structure" on page 3.15 for available alarms.

- When outside the alarm parameters, the relevant warning will flash lower left corner of the screen.
- Volume rate alarm for over or under application activates after 20 seconds.

| Menu | 2.5. 1 | ESC |
|--------------------------|---------|----------|
| Volume rate alarm | | |
| Tank contents at minimum | | T |
| Spray pressure | | |
| Fan speed alarm | | |
| Speed alarm | | |
| Wind Speed | | 1 |
| PTO r/min alarm | | |
| R/minute alarm | | |
| Over or under applicatio | on alar | |

The warnings appear as shown. For more details on warnings, see "Fault codes" on page 11.5.



NOTE! The HC 9500 shows the warnings in the top bar of the screen. Other ISOBUS screens may vary.



Menu 3.1 Speed calibration

The calibration process is the same for each sensor type. In the following example a "speed sensor on sprayer" (Menu 3.1.1 Sprayer) is used.

The menu can be reached by navigating via the menu structure.

Navigating the menu

- 1. From menu [3 Calibration] the menu [3.1 Speed calibration] should be selected.
- 2. Select one of the following menus corresponding to desired speed sensor:
 - [3.1.1 Sprayer] Speed sensor on sprayer
 - [3.1.2 Tractor] Speed sensor on tractor (use for GPS speed)
 - [3.1.3 Radar] Radar speed sensor
- 3. The last confirmed sensor is the active speed sensor.
- 4. Choose submenu.



It is possible to calibrate the speed sensor in different ways. You may enter a theoretical speed constant or perform a practical calibration.

Select calibration method in the two submenus

| Menu | Function |
|---------|-----------------|
| 3.1.1.1 | Speed constant |
| 3.1.1.2 | Speed practical |

Select one of the calibration methods using the navigation keys, then press Enter to accept.

The procedure for each menu is described in the following sections.

ATTENTION! The practical method is recommended.





Menu 3.1.1.1 Sprayer speed constant

The theoretical speed constant, pulses per unit (PPU), is the number of times the speed sensor records holes (or protrusions / magnets) per foot (meter) as the wheel rotates past the sensor. If necessary, this can be calculated by dividing the number of protrusions by the circumference of the tire in feet (meters).

By using known tire dimensions and number of protrusions, the following formulas may be used to calculate the theoretical PPU:

PPU (feet)

$$PPU = \frac{Protrusions \times 12}{\pi \times \left(\frac{Tirewidth \times Ratio}{1270} + Rimheight\right)}$$

PPU (meter)

$$PPU = \frac{Protrusions \times 1000}{\pi \times \left(\frac{Tirewidth \times Ratio}{50} + Rimheight \times 25.4\right)}$$

Example

If changing tires on a Commander 7000 (36 protrusions) to a 320/90R50 tire, the PPU (feet) is calculated as follows:

$$PPU = \frac{36 \times 12}{3.14159 \times \left(\frac{320 \times 90}{1270} + 50\right)} = 1.892$$

) ATTENTION! The practical method is recommended.

Menu 3.1.1.2 Sprayer speed practical

Practical calibration of speed is done by driving a measured distance and correcting the display so that the actual and the calculated distances are the same.



NOTE! Calibration should take place in the field with a half full tank and normal working tire pressure in order to obtain the wheel's real "working radius".

ATTENTION! Changing tires will require a new calibration!

Method

- 1. Measure a distance not less than 200 feet.
- 2. Park the tractor at the start of the measured distance.
- 3. Press Enter. When zero distance [0] shows, drive the distance.
- 4. Press Enter.
- 5. Correct the distance shown on the display to read the actual distance.
- 6. Press Enter to see the new calculated value.
- 7. Press Enter again to accept the value.
- 8. Repeat process to verify calibration. PPU should not change significantly if calibration has been made correctly.





Menu 3.2 Flow calibration

The flow transducer can be calibrated theoretically or calibrated with clean water by using one of the two practical methods.

The practical methods are preferred:

| Method | Calibration time | Accuracy |
|---------------|------------------|------------|
| Tank method | Time consuming | Accurate |
| Nozzle method | Short | Inaccurate |



(hs)

ATTENTION! When changing to nozzles with more than a 100% increase or decrease in output, it is recommended to re-calibrate the flow transducer.

| Menu | 3.2 | ESC |
|--------------------------------|-----|-----|
| Speed calibration | | |
| Flow calibration | | T |
| Boom setup | | |
| Regulation constant | | |
| Tank gauge calibration | | |
| Track calibration | | L . |
| LookAhead calibration | | |
| LookAhead custom nozzles | | |
| | | |
| Flow sensor calibration. Theor | | |
| etical (PPU), Nozzle Tank meth | | |
| od PrimeFlow | | |

ATTENTION! Calibration is recommended to be done at least once during the spraying season. Use the chart "Chart for recording values" on page 13.4 to record the values.

Menu 3.2.1 Flow constant

When spraying both fertilizer and chemical, HARDI[®] recommends to use 2 different flow sensor housings in order to get good pressure regulation. The same flow sensor wheel is used for both flow sensor housings. Flow sensor calibration PPU must be changed each time flow sensor housings are changed.

Correct flow housing can easily be selected based on:

- Sprayer boom width.
- Operator's typical spray pressure in the field (max. pressure).
- Nozzle ISO size typically selected by operator.

Approximate PPU values for different flow housings are listed in the table below. Different flow housings are designated by groove (A).

| Housing | Housing identification (A) | Flow range | Orifice | PPU |
|---------|----------------------------|------------|---------|--------|
| | | g/min | mm | value |
| S/67 | One outside groove | 2 - 30 | 13.5 | 430.00 |
| S/67 | No groove | 4 - 70 | 20.0 | 215.00 |
| S/67 | Two outside grooves | 20 - 160 | 36.0 | 60.00 |





To change the theoretical flow constant, use the navigation keys to enter a new PPU value.

ATTENTION! PPU indicates the number of pulses which theoretically come from the flow transducer while 1 gallon of liquid passes through.

ATTENTION! Entering a theoretical PPU value does not guarantee accuracy. Flow calibration should still be carried out using one of the practical methods.

Flow rate charts for various spraying pressures

| Flow rates at 40 psi spraying pressure | | Flow (gpm) by Boom size (20" nozzles) | | | | | | | |
|--|------------|---------------------------------------|--------|--------|--------|-------|-------|-------|-------|
| Nozzle | Flow (gpm) | Flow housing | 132 ft | 120 ft | 100 ft | 90 ft | 80 ft | 66 ft | 60 ft |
| Pink ISO 0075 | 0.075 | One groove Ø13.5 mm | 6 | 5.4 | 4.5 | 4.0 | 3.6 | 3 | 2.7 |
| Orange ISO 01 | 0.100 | One groove Ø13.5 mm | 8 | 7.2 | 6 | 5.4 | 4.8 | 4 | 3.6 |
| Green ISO 015 | 0.150 | One groove Ø13.5 mm | 12 | 10.8 | 9 | 8.1 | 7.2 | 6 | 5.4 |
| Yellow ISO 02 | 0.200 | One groove Ø13.5 mm | 16 | 14.4 | 12 | 10.8 | 9.6 | 8 | 7.2 |
| Lilac ISO 025 | 0.250 | One groove Ø13.5 mm | 20 | 18 | 15 | 13.5 | 12 | 10 | 9 |
| Blue ISO 03 | 0.300 | No groove Ø20 mm | 24 | 21.6 | 18 | 16.2 | 14.4 | 12 | 10.8 |
| Red ISO 04 | 0.400 | No groove Ø20 mm | 32 | 28.8 | 24 | 21.6 | 19.2 | 16 | 14.4 |
| Brown ISO 05 | 0.500 | No groove Ø20 mm | 40 | 36 | 30 | 27 | 24 | 20 | 18 |
| Grey ISO 06 | 0.600 | No groove Ø20 mm | 48 | 43.2 | 36 | 32.4 | 28.8 | 24 | 21.6 |
| White ISO 08 | 0.800 | Two grooves 36 mm | 64 | 57.6 | 48 | 43.2 | 38.4 | 32 | 28.8 |
| Light blue ISO 10 | 1.000 | Two grooves 36 mm | 80 | 72 | 60 | 54 | 48 | 40 | 36 |

Flow rates at 60 psi spraying pressure Flow (gpm) by Boom size (20" nozzles) 66 ft Nozzle Flow (gpm) Flow housing 132 ft 120 ft 100 ft 90 ft 80 ft 60 Pink ISO 0075 0.092 One groove Ø13.5 mm 7.4 6.6 5.0 4.4 3.7 3.3 Orange ISO 01 0.122 9.8 8.8 7.3 6.6 5.9 4.9 4.4 One groove Ø13.5 mm Green ISO 015 0.184 One groove Ø13.5 mm 14.7 13.2 11.0 9.9 8.8 7.4 6.6 0.245 Yellow ISO 02 19.6 17.6 14.7 9.8 8.8 One groove Ø13.5 mm 13.2 11.8 Lilac ISO 025 0.306 No groove Ø20 mm 24.5 22.0 18.4 16.5 14.7 12.2 11.0 17.6 Blue ISO 03 0.367 29.4 26.4 22.0 19.8 14.7 13.2 No groove Ø20 mm Red ISO 04 0.490 No groove Ø20 mm 39.2 35.3 29.4 26.5 23.5 19.6 17.6 Brown ISO 05 0.612 No groove Ø20 mm 49.0 44.0 36.7 33.0 29.4 24.5 22.0 Grey ISO 06 0.735 Two grooves Ø36 mm 58.8 52.9 44.1 36.7 35.3 29.4 26.5 White ISO 08 0.980 78.4 58.8 47.0 Two grooves Ø36 mm 52.9 39.2 35.3 Light blue ISO 10 1.225 58.8 49.0 44.1 Two grooves Ø36 mm 66.2

| Flow rates at 70 psi spraying pressure | | Flow (gpm) by Boom size (20" nozzles) | | | | | | | |
|--|------------|---------------------------------------|--------|--------|--------|-------|-------|-------|-------|
| Nozzle | Flow (gpm) | Flow housing | 132 ft | 120 ft | 100 ft | 90 ft | 80 ft | 66 ft | 60 ft |
| Pink ISO 0075 | 0.099 | One groove Ø13.5 mm | 7.9 | 7.1 | 5.9 | 5.3 | 4.8 | 4.0 | 3.6 |
| Orange ISO 01 | 0.132 | One groove Ø13.5 mm | 10.6 | 9.5 | 7.9 | 7.1 | 6.3 | 5.3 | 4.8 |
| Green ISO 015 | 0.198 | One groove Ø13.5 mm | 15.8 | 14.3 | 11.9 | 10.7 | 9.5 | 7.9 | 7.1 |
| Yellow ISO 02 | 0.265 | No groove Ø20 mm | 21.2 | 19.1 | 15.9 | 14.3 | 12.7 | 10.6 | 9.5 |
| Lilac ISO 025 | 0.331 | No groove Ø20 mm | 26.5 | 23.8 | 19.9 | 17.9 | 15.9 | 13.2 | 11.9 |
| Blue ISO 03 | 0.397 | No groove Ø20 mm | 31.8 | 28.6 | 23.8 | 21.4 | 19.1 | 15.9 | 14.3 |
| Red ISO 04 | 0.529 | No groove Ø20 mm | 42.3 | 38.1 | 31.7 | 28.6 | 25.4 | 21.1 | 19.0 |
| Brown ISO 05 | 0.661 | Two grooves Ø36 mm | 52.9 | 47.6 | 39.7 | 35.7 | 31.7 | 26.4 | 23.8 |
| Grey ISO 06 | 0.794 | Two grooves Ø36 mm | 63.5 | 57.2 | 47.6 | 42.9 | 38.1 | 31.8 | 28.6 |
| White ISO 08 | 1.058 | Two grooves Ø36 mm | 84.6 | 76.2 | 63.5 | 57.1 | 50.8 | 42.3 | 38.1 |
| Light blue ISO 10 | 1.323 | Two grooves Ø36 mm | 105.8 | 95.3 | 79.4 | 71.4 | 63.5 | 52.9 | 47.6 |

Menu 3.2.2 Nozzle method

Compares the individual nozzle output on the display to the actual individual nozzle output. The output displayed is corrected to read the actual output.



ATTENTION! See menu [3.3 Boom] if no boom data has yet been entered.

Method

- 1. Open all boom sections. Switch the main ON/OFF to ON. Close End nozzles (if fitted).
- 2. Go to menu [3.2.2 Nozzle method].
- **3.** Press Enter. The display will then show the individual nozzle output per minute.





ATTENTION! If a section has not been opened or an end nozzle is not closed, a warning will show up in the largest window on the display.

- 4. Using a HARDI® calibration jug, check the actual nozzle output per minute. It is recommended that an average of several nozzles be taken.
- 5. Press Enter.
- 6. Correct the output shown on the display to read the average output measured with the calibration jug.
- 7. Press Enter to see the new value.
- 8. Press Enter again to accept the value.

Menu 3.2.3 Tank method

The tank is partly emptied through the nozzles while the display calculates the quantity emptied on the basis of the actual calibration value (PPU). The quantity displayed is corrected to read the actual measured quantity emptied.

This can be done according to the tank contents level indicator or by weight difference before and after.



The shown volume

is adjusted to match the actua

Press Enter.

l volume

Method

- 1. Fill the sprayer with a known amount of water, e.g. 500 gallons. It is recommended to weigh the sprayer before and after filling in order to get an exact value.
- 2. Open all boom sections.
- 3. Go to menu [3.2.3 Tank method], press Enter and switch the main ON/OFF to ON.
- 4. The display unit will then begin to count the volume being emptied through the nozzles.
- 5. When, for example, 300 gallons have been emptied out as shown by the tank contents level indicator, then switch the main ON/OFF to OFF. Weigh the sprayer again to get the exact volume sprayed out.
- 6. Press Enter.
- 7. Correct the volume shown in menu 3.2.3.2 on the display to read the actual measured volume emptied.

- 8. Press Enter to see the new value.
- 9. Press Enter again to accept the new value.



Menu 3.3 Boom

Menu 3.3.1 Width

- 1. Set boom width.
- 2. Press Enter to confirm.



- 1. Set number of boom sections.
- 2. Press Enter to confirm.







Menu 3.3.3 Nozzles/sections

- 1. Set correct number of nozzles per section.
- 2. Press Enter to continue to next boom section.
- 3. Press Enter after the last section.

Menu 3.3.4 End nozzles and Bi-jet (optional)

If end nozzles or Bi-jet are fitted, it should be set up corresponding to the number of boom nozzles it covers.

- 1. In menu [3.3 Boom setup] go to the menu [3.3.4 End nozzles and Bi-jet].
- 2. Press Enter.
- 3. Select submenu corresponding to the type of end nozzle:

| Menu | Function |
|---------|--------------------|
| 3.3.4.1 | None |
| 3.3.4.2 | End nozzles fitted |
| 3.3.4.3 | Bi-jet fitted |



- 4. Press Enter.
- 5. In the sub menus [3.3.4.2] and [3.3.4.3] set the value to the equivalent coverage by the boom nozzles. E.g. end nozzle coverage is 5 feet. This is equal to 3 boom nozzles.
- ATTENTION! It is important that the volume applied from the end nozzle matches the volume applied under the boom, i.e. end nozzles mounted must have the same ISO size as the regular nozzles on the boom. This is a comparison of volume per minute per length (Gallons/min/inches).

When the end nozzle is active, the area covered and volume sprayed is calculated and registered. If "Active boom size" is displayed, it will show an increase when the end nozzle is activated.

| The table below is based off data from the flatar mozzle product quide and is valid at ± 5 psi (5 bar). |
|---|
|---|

| End nozzles | Width (inches) | Total flow/nozzle (gpm) | Equivalent ISO nozzle size | 20" flow/nozzle (gpm) |
|--------------------------|----------------|-------------------------|----------------------------|-----------------------|
| 1850 End nozzle 3/8" - 9 | SYNTAL | · | | · |
| 1850 G-150 | 61 | 0.274 | Pink ISO 0075 | 0.09 |
| 1850 G-200 | 77 | 0.449 | Orange ISO 01 | 0.12 |
| 1850 G-250 | 98 | 0.777 | Green ISO 015 | 0.16 |
| 1850 G-300 | 110 | 0.970 | Green ISO 015 | 0.18 |
| 1850 G-350 | 116 | 1.480 | Lilac ISO 025 | 0.26 |
| 1850 G-400 | 136 | 2.039 | Blue ISO 03 | 0.30 |

Menu 3.3.5 Length hitch to axle for ASC

Set length from the tractor's hitch eye to the sprayer's wheel axle. The distance is used when determining the path of the spray rig as it moves around in the field.



ATTENTION! This menu is only for sprayers equipped with ISOBUS and AutoSectionControl.



Menu 3.3.6 Length axle to boom for ASC

Set length from the sprayer's wheel axle to the boom, measured at the nozzles. The distance is used when determining the path of the spray rig as it moves around in the field.



ATTENTION! This menu is only for sprayers equipped with ISOBUS and AutoSectionControl.



ESC

t

3.4. 1

Regulation user setup

Simulated speed value Nozzle size flow at 3 bar

Dual line second nozzle

Flow to obtain 1 bar pressure drop over pressure filter and

Type of nozzle Regulation parameter

flow sensor

Menu

Menu 3.4 Regulation user setup

The sensitivity of pressure regulation valve can be adjusted. Values are to be set for obtaining precise regulation, even if sensors fails.

The valve is controlled by up to five main sensors:

- Sprayer speed sensor: This sensor reads the sprayer's forward speed which is used for calculating the volume rate at all spraying speeds.
- Flow sensor: This sensor reads the flow at the operating unit which is used for calculating the pressure at all flow rates.
- Pressure sensor: This sensor reads the pressure at the operating unit which is used for calculating the flow at the pressure regulation valve.
- P.T.O. RPM sensor: This sensor reads the pump RPM's which is used to calculate the flow from the pump at all pump speeds.
- Regulation valve opening angle sensor: This sensor reads the opening angle for the rotary valve inside. When opening angle is known, the flow can be calculated when the pressure is also known. The result is when forward speed, pump RPM's, etc. is known, then the regulation valve can predict setting (Feed Forward) before opening the main ON/OFF. Thereby the volume rate is correct even the forward speed has changed significantly since the main ON/OFF was closed (no fluctuation).

Menu 3.4.1 Flow sensor restriction

The menu defines the resistance in the plumbing and circuits of the specific sprayer setup. As the resistance varies with the choice of flow housing, this must be set up prior to spraying.

• Select value from the schematic and enter it in this menu.

| Flow housing | Flow |
|--------------------------|----------|
| HARDI® 13.5 mm | 26.2 gpm |
| HARDI [®] 20 mm | 41.2 gpm |
| HARDI® 36 mm | 48.1 gpm |

• Default value: 41.2 gpm (156 l/min)



Menu 3.4.2 Simulated speed value

The "Simulated speed value" menu is used in 2 situations:

 When stopped or driving very slowly while priming the boom.

This feature allows the operator to stop or drive slowly and automatically get normal spray pressure to prime the boom.

• If speed sensor is defective. In this case the computer will assume that the sprayer is traveling with the speed typed in "Simulated speed value". The operator should keep the tractor constantly at this speed to maintain a good regulation with ability to handle changes in application rate and changes in sections.

Speed entered should be appropriate also for headlands. If speed is reduced at headlands, resulting application rate will be higher than set value. I.e if operator selects application rate of 20 gpa and speed of 5 mph and then reduces speed from 5 to 4 mph at headlands, actual application rate will increase to 25 gpa.

Also when spraying speed drops below the lowest speed where a spray job can begin when starting at headland (this speed is set by the HARDI[®] dealer), the speed will be simulated to maintain normal spray pressure until normal spraying speed is maintained.

• Default value: 4.5 mph (7.2 km/h)



ATTENTION! Use this menu when a spray job has to be finished before fixing the defective sensors.

ATTENTION! Recommended setting is 75-90% of spraying speed.



Menu 3.4.3 Nozzle size flow at 45 psi

In fault free operation, the controller uses the flow sensor and the pressure sensor to detect the nozzle size.

In case of flow sensor and/or pressure sensor fault, the nozzle flow can be entered to obtain a more accurate regulation of the regulation valve.

If either the flow sensor or the pressure sensor is faulty, the nozzle cannot be identified. The controller stores the last detected nozzle size, and this value is then used.

• Default value: 0.21 gpm (0.80 l/min)



ATTENTION! If changing nozzles while a sensor is faulty, then type in the size of the new nozzle.



Nozzle size is defined as flow at 3 bar as to be seen in the Hardi® nozzle catalog.

1 NOTE! The flow at 45 psi in the Hardi[®] nozzle catalog is measured without nozzle filter and without Pentalet nozzle holder. The flow restriction from these 2 make the nozzle appear smaller, see table below.

| Nozzle | Flow (gpm) |
|---------------|------------|
| 0075-Pink | 0.08 |
| 010-Orange | 0.11 |
| 015-Green | 0.16 |
| 020-Yellow | 0.21 |
| 025-Lilac | 0.26 |
| 03-Blue | 0.32 |
| 04-Red | 0.42 |
| 05-Brown | 0.53 |
| 06-Grey | 0.63 |
| 08-White | 0.85 |
| 10-Light blue | 1.06 |

Menu 3.4.4 Dual line second nozzle (not used in North America)

Menu 3.4.5 Type of nozzle

Select the nozzle type to be used when spraying.

• Default value: Regular nozzle.



ATTENTION! Remember to change the specific gravity of the chemical mix in menu [3.5.1 Adjustment of specific gravity].

| Type of nozzle | 101010 | esc |
|----------------------|-----------|----------|
| Menu | 3.4.5. 1 | |
| Regular nozzle | | |
| QuintaStream | | T |
| | | _ |
| | | |
| | | T |
| | | |
| | | |
| | | |
| | | |
| Flat fan, Low drift, | Minidrift | |
| | | |

Menu 3.4.6 Regulation parameter

Code for special machines or applications, consult your HARDI® Service Center.

• Default value: Code 1



Menu 3.5 Tank gauge

Present accuracy is up to +/-7 gallons. This is at the widest liquid surface area in the tank. The smaller the liquid surface area, the more accurate the readout.



ATTENTION! For increased accuracy it is recommended to do the flow calibration (menu 3.2) before proceeding.



ATTENTION! This menu item is only present if the HARDI® Tank Gauge is fitted.

| Menu | 3.5. 2 | ESC |
|----------------------------|--------|-----|
| Adjustment of specific gra | | |
| Calibration of Tank gauge | | T |
| Select factory calibration | - | |
| offset at empty Hainfank | | |
| | 1 | |
| | | |
| | | |
| | | _ |
| | | |
| Calibrate if factory calib | orati | |
| on is not adequate | | |

Menu 3.5.1 Adjustment of specific gravity

The correction factor for the specific gravity of the liquid sprayed can be set.

Default value is 1.00.

Corrected value is weight of solution divided by weight of water.

For liquid fertilizers, the specific gravity may range up to 1.3 times heavier than water. The value in this case would be 1.30.



ATTENTION! Remember to set type of nozzle to be used in menu [3.4.5 Type of nozzle].

Method

- 1. Set specific gravity.
- 2. Press Enter to confirm.

Menu 3.5.2 Calibration of Tank gauge

ATTENTION! Prior to attempting a custom calibration, the SafeTrack must be disabled in the extended menu.

Calibration of the HARDI® Tank Gauge is necessary if the factory calibration shows inaccurate. E.g. different placed hitch point on the tractor or other tire mounting may result an inaccurate calculation of the tank contents.

Therefore it is recommended to begin the custom calibration by connecting the sprayer to the tractor that will be used for spraying. Later changes of tractor can affect the accuracy of the Tank gauge.



Custom calibration

1. First enter menu [3.5.3.01 Custom calibration of gauge].



- 2. Go to menu [3.5.2.1 Water level].
- **3.** Fill the sprayer up to nominal tank contents, using an external calibrated flowmeter. Alternatively weigh the sprayer before and after filling, and note the weight difference.
- 4. Press Enter.
- ATTENTION! As the accuracy of the custom calibration is affected, it is of high importance that the external calibrated flowmeter measures the correct quantity within a 2% deviation. Same accuracy of 2% must be kept if weighing the sprayer before/after filling is used.



WARNING! Do not leave the sprayer while filling the tank, and keep an eye on the level indicator in order NOT to overfill the tank.

5. Press Enter after ensuring the sprayer is level. Refill the tank up to the tank lid if the sprayer is re-levelled.





ATTENTION! Levelling the procession of sprayer is of great importance as the accuracy is directly affected!

Assuming that the same tractor will be used after custom calibration, it is not necessary for the sprayer to be level itself. But the whole procession of tractor and sprayer (A) need to be level.

Use e.g. a beam (B) approximately 20 feet long, placed on two wooden blocks at the location where the calibration will take place. Place a level (C) on the beam (B) to find the level point of the calibration location.



- 6. Engage the pump and set P.T.O. revolutions at 540 rpm or 1000 rpm (depending on pump model).
- 7. Open all boom sections and empty the tank. The pulses from the flow transducer are logged as data points.

During this session the screen shows:

[xxxx] as the actual water level in inches and

[yyyyyyy] is the number of pulses from the flow meter.



- ATTENTION! The definition of having an empty tank, is when no spray comes out of the nozzles anymore. Note that when empty, there will still remain about 3 gallons in the sump of the tank.
 - 8. Press Enter when the tank is empty.
 - 9. Correct the displayed volume to the actual volume sprayed out.
- **10.** Press Enter. The new custom gauge table is calculated and the calibration of the HARDI® Tank Gauge is finished.



Menu 3.5.3 Select factory calibration

This menu may have been set up by your HARDI® service center. Selection can only be done with no water in the tank. See "Menu 3.5.4 Offset at empty main tank" to check if empty.

The prerequisites for accuracy of the level, when selecting the factory calibration is:

• Level sprayer; When mounted to the tractor then the sprayer should be level.

Check if level by placing a level on the frame of the COMMANDER sprayer as follows:

COMMANDER model Place of level

| 5500 or smaller | Underside of the frame. |
|-----------------|---|
| 8500 or larger | Upper side of the frame (Important as frame is not parallel). |

Height of hitch point when mounted to tractor; The height of hitch point measured from the ground should be 21.7" (550 mm). Measure of tank contents changes with the height of the hitch point.



ATTENTION! If one of the prerequisites are not fulfilled, then refer to "Menu 3.5.2 Calibration of Tank gauge" to make a custom calibration of the tank gauge.

| Menu | 3.5.3. 4 | csc |
|-------------------------|----------|-----|
| Custom calibration of | gauge | |
| CME3300 factory calibra | ation | Т |
| CME4500 factory calibra | ation | |
| CME7000 factory calibra | ation | ▰ |
| CME9000 factory calibra | ation | |
| Alpha 2500 factory call | ibration | T. |
| Alpha 3500 factory cal | ibration | V |
| Alpha 4100 factory cal: | ibration | |
| Alpha 3000 factory cal | ibration | |
| Factory tank gauge tab | Le for C | |

Menu 3.5.4 Offset at empty MainTank

In menu [3.5.4.1 TankGauge Offset] read out the frequency (Hz) at empty tank. If the main tank is empty, then press Enter to accept the frequency.

In case the main tank is not empty, this menu can only be used to correct the empty-frequency if it is known to the user.

1

NOTE! The definition of an empty tank is when the pump is not able to suck more liquid from the tank, i.e. there will still be a very small amount of liquid in the sump when the tank is defined empty.



ATTENTION! This can also be useful for re-calibrating empty tank frequency if the sensor has dirt on it.



Menu 3.6 Track

There is no standard setting for the Track setup. The Track needs to be adjusted for different kinds of tractors, the sprayer and spraying practices and can only be found under actual conditions.

| Spraying speed | Track setup |
|---------------------------|---|
| High speed (12 to 16 mph) | Must react slowly: The dead zone must be increased. |
| Low speed (4 to 6 mph) | For high precision: The dead zone can be reduced. |

For each adjustment, it's described what happens if the setting is changed and what effect will it have on the sprayer.

SafeTrack

SafeTrack is operated at the SetBox.

Track selection switches has 3 functions:

- 1. Align button (16) will align the sprayer. Used before folding the boom.
- 2. Auto button (17) switches SafeTrack into auto mode and the sprayer will follow the track from the tractor.
- 3. Manual buttons (15) will steer the sprayer right and left. Auto is OFF when using manual buttons (15).



ATTENTION! If unsafe driving occurs, an alarm will be triggered and the sprayer will align.

- Press Enter to turn alarm off.
- Pressing "align" (16) will also turn alarm off. Be aware that the alarm cannot be turned off as long as unsafe driving still occurs!

Menu 3.6.1 Track width

Here the track width can be entered.

• The track width is measured from right side tire center to left side tire center of the sprayer wheels.

It is important that the correct track width is entered. The controller will calculate the speed at the center of sprayer, and not at the wheel sensor as speed would vary in right and left turns.



ATTENTION! If the track width is incorrect, it will influence on track precision and the safety factor.



Factory setting: 71" (180 cm)

Menu 3.6.2 Tractor drawbar

Here the length of the tractor drawbar is entered.

• The measurement is from the center of the tractor rear axle to the center of the drawbar pin.

This has to be adjusted every time a new tractor is hooked on to the sprayer. When hooked up, check the rigidity of the tractor drawbar mounts. There must be no sideways movement.

Factory setting: 31" (80 cm)

| Too short measurement: | The Track reacts faster, but will make the |
|------------------------|--|
| | sprayer steer too large curves. |
| Too long measurement: | The Track reacts slower, but will make the |
| | sprayer steer too short curves. |

Menu 3.6.3 Dead zone for regulation

This is the non regulation zone when the sprayer is straight behind the tractor. If the sprayer is oscillating in the hydraulics when driving straight, this value must be increased.

Factory setting: 4" (10 cm); Over 8" (20 cm) not recommended.

Decreasing value:Reacting on small deviations. Tendency to
oscillation that will damage the boom.
High precision, but more unstable driving
with small corrections all the time.Increasing value:No oscillation but tendency to sway. Low
precision, but very steady driving with less
corrections.

Menu 3.6.4 Damping of hydraulics

If the system is to aggressive the damping constant must be increased. Failure to do so may damage the boom.

Factory setting: 50%

| No damping (0%): | High precision, but very unsteady. Fast |
|----------------------|--|
| | reaction time, but more aggressive |
| | movement that potentially can damage |
| | the boom. |
| Full damping (100%): | Low precision, but very steady. Slow reaction time, but less aggressive. |

Menu 3.6.5 Align offset + right - left

This is to compensate if the front potentiometer is placed offset to the center line when the sprayer is attached.

Factory setting: 0" (0 cm)

Negative setting will move the sprayer to the left of the track, and positive setting will move the sprayer to the right of the track. The sprayer must follow the tractor in a straight line in all situations. If the value is over 4" (10 cm), it is recommended to manually adjust position of the front angle sensor.









Menu 3.6.6 Calibrate sensitivity

This adapts the track regulation to the tractor hydraulics and to the characteristics of the sprayer hydraulics system.

Calibration procedure is divided into 4 parts where an offset and gain value is found to both left and right movement, 4 values in all.

Method

- 1. Unfold boom and, without driving, set P.T.O. to spraying R.P.M.
- 2. Align sprayer and press in to enable "auto" at the SetBox. First left/right offset is found:
- **3.** Go to menu [3.6.6 Sensitivity] and select "Yes" and press Enter. Press Enter again and calibration starts.
- 4. Press and hold the manual "steer to right" button (A).





5. Display will show a counting percentage.



6. When offset is found it ends with an "OK" message.



7. Press and hold the manual "steer to left" button (B).



6⁰¹

ESC

(A)

8. Display will show a counting percentage.

- 9. When offset is found it ends with an "OK" message.
- 01 6 outo 3 left side 3.6.6.6 26

.

- 10. Then calibration automatically continues with gain calibration. Press and hold the manual "steer to right" button (A).

outo

11. Display will show a counting percentage.



SafeTrack



12. When offset is found it ends with an "OK" message.

13. Press and hold the manual "steer to left" button (B).

14. Display will show a counting percentage.



15. The display reads "Calibration is OK" when calibration has finished. Confirm and leave menu by pressing Enter.



Emergency Track

If a problem with the Track should occur, please see "Menu 4.7 Emergency Track".

Menu 4 Toolbox

Menu 4.1 Measure

This is a simple electronic trip meter. You can measure distance. If the implement width is entered in menu [4.1.3 Working width], area can also be measured in menu [4.1.2 Area].

1. Press Clear to clear the value.

Following submenus are possible:

| [4.1.1 Measure Distance] | Measures a distance being travelled. |
|-----------------------------|--|
| [4.1.2 Measure Area] | Measures the area the boom covers at a travelled distance. |
| [4.1.3 Setup working width] | Menu for entering the boom working width to be measured. |
| [4.1.4 Stop-watch] | Measures the time being used. |
| [4.1.5 Alarm clock] | Can give an alarm at a preset time. |

Menu 4.2 Service intervals

Service intervals and a nozzle check are programmed into the Controller. This makes it easier for the operator to remember the service intervals.

From the factory, the Controller is set up with three service and a nozzle check reminder.

| Menu & interval | Hours | Action | |
|---------------------------------|-------|---|--|
| [4.2.1 Check filters] | 10 | See sprayer instruction book, Maintenance. | |
| [4.2.2 Grease boom] | 50 | See sprayer instruction book, Maintenance. | |
| [4.2.3 Grease track and center] | 250 | See sprayer instruction book, Maintenance. | |
| [4.2.4 Miscellaneous service] | 0 | Not defined from factory. | |
| [4.2.5 Check nozzles] | 10 | Check flow rate. Change nozzles if more than 10% of rated flow. | |

Entering the above menu's will display the hours remaining until next service. The importer or dealer may have added a "Miscellaneous service" interval. If no interval is set, [Miscellaneous service not defined] is shown.

Press Enter to register service or control, if displayed when switched on. The warning Λ will remain present until the service interval is reset.

Menu 4.3 Service interval reset

To reset service interval, go to relevant interval menu listed:

| Menu & interval | Hours | Action | |
|---------------------------------|-------|---|--|
| [4.2.1 Check filters reset] | 10 | See sprayer instruction book, Maintenance. | |
| [4.2.2 Grease boom reset] | 50 | See sprayer instruction book, Maintenance. | |
| [4.2.3 Grease track and center] | 250 | See sprayer instruction book, Maintenance. | |
| [4.2.4 Miscellaneous service] | - | Not defined from factory. | |
| [4.2.5 Check nozzles] | 10 | Check flow rate. Change nozzles if more than 10% of rated flow. | |

- 1. Press Clear to reset hour meter.
- 2. Press Enter to confirm.

Menu 4.4 Reserved

Reserved function - This menu is not used

8 - Menu 4 Toolbox

Menu 4.5 Test

All readouts for the transducers are in accumulated counts, i.e. one signal gives one count, except for the optional (analog) transducer that is read in milliampere.

- 1. Go to menu [4.5 Test].
- 2. Choose the item to be tested and open the menu.
- 3. Activate sensor and see if the signal is detected.

| Menu | Help text | |
|-----------------------------------|---|----------------|
| 4.5.1 Flow Speed Optional sensors | Activate function to monitor sensor (e.g. drive forwards, start flow). | |
| 4.5.2 Active keys | Push key to see if a count is registered. If yes, the key or switch function is OK. | |
| 4.5.3 PrimeFlow test | PrimeFlow test for nozzles and PrimeFlow computers on boom. | Not for ISOBUS |
| 4.5.4 Input test | See computer readings of sensors. Frequency, switch, analog inputs. | |
| 4.5.5 Valve test | Self test. | |
| 4.5.6 PrimeFlow SMCU status | See nozzle position, nozzle order, counts of data error power error. | |
| 4.5.6 PrimeFlow motor status | See nozzle motor status. | |

Menu 4.6 Speed simulation

Speed may be simulated for certain purposes. A two figure value may be entered. The state remains valid until the Controller is restarting or the value is set to "0".


Menu 4.7 Emergency

This menu bypasses the system so all sensors are ignored. Then it is possible to align the sprayer or fold the boom manually and drive home. The sensor status and voltages can be checked, which is useful for HARDI® service to solve the problem.

Menu 4.7.1 Track align

The sensor status and voltages can be checked when aligning the sprayer.



NOTE! Values shown in illustration is an example only.

| Menu | 4 7 1 | ESC |
|---|-------------------|-----|
| henu | 4.7.1 | |
| Front sensor | 0.01 | |
| Front sensor | 0.0 | |
| Rear sensor | 0.00 | |
| Rear sensor | 0.0 | |
| Boom sensor 1 | 0.00 | |
| Boom sensor 1 | 1 | |
| Lock sensor | 0.00 | |
| Lock sensor | 1 | |
| SafeTrack mode | 2 | |
| Emergency only. Align s and fold boom, in case | prayer a senso | |
| r is defect | | |

Menu 4.7.2 Boom fold

The sensor status and voltages can be checked when folding the boom.



NOTE! Values shown in illustration is an example only.

| Menu | | | ESC |
|-----------|------------|-------|-----|
| | | 4.7.2 | |
| Dynamic c | entre pos. | 0.00 | |
| Dyn. cent | re | 99 | |
| Pendulum | lock | 0.00 | |
| Pend. unl | ock | 0.0 | |
| Boom sens | or 1 | 0.00 | |
| Boom sens | or 1 | 1 | |
| Boom heig | ht status | 0 | |
| Boom heig | ht | 0.00 | |
| Boom hydr | aulics | 2 | |

Lock sensor:

| Lock sensor indication | Track selection switch | Left/right steer | Fold inner |
|-------------------------|------------------------|------------------|------------|
| Released (high voltage) | Auto or Manual | Possible | Possible |
| Locked (low voltage) | Auto or Manual | Not possible | Possible |

If the track selection switch is switched to "align" the trapeze lock is attempted locked disregard any sensor reading. No automatic align is attempted. Manual or automatic tracking is not possible.

Once the boom is folded into transport position, exit the menu. This will activate the track lock if it is not damaged. As an extra security, stop oil flow to the sprayer and switch power to OFF on the SetBox in order to turn off the JobCom.



DANGER! Emergency only. Don't track with the boom folded! Safety system is disabled.

Menu 4.8 Computer CAN status

In this menu you can see if there is communication between the units, Controller, Jobcom and Track. See part "Emergency operation".

Menu 4.8.X Computer CAN status:

| [4.8.1 Operating status all computer] | Show operating status details in case of faults. | | |
|--|---|------------------------------------|----------------|
| [4.8.2 Software versions all computer] | Show software versions details in case of faults. | | |
| [4.8.3 Hardware versions all computer] | Show hardware versions details in case of faults. | | |
| [4.8.4 Work status Terminal HC 6500] | Show faults occurred since power-up. | Press Clear key to reset counters. | |
| [4.8.5 Work status JobCom HC 6100] | Show faults occurred since power-up. | Press C key to reset counters. | Not for ISOBUS |
| [4.8.6 Work status Grip HC 6300] | Show faults occurred since power-up. | Press C key to reset counters. | Not for ISOBUS |
| [4.8.7 Work status SetBox HC 6400] | Show faults occurred since power-up. | Press C key to reset counters. | Not for ISOBUS |
| [4.8.8 Work status FluidBox HC 6200] | Show faults occurred since power-up. | Press C key to reset counters. | Not for ISOBUS |

8 - Menu 4 Toolbox

Menu 5 Logbook

Menu 5.1 Print

This menu has to do with printing of data. The following can be printed via the 12 volt printer.

| Menu | Help text |
|--------------------------------------|--|
| [5.1.1 Print single register] | A specific register is selected for a print. |
| [5.1.2 Print all registers] | Register in use will be printed. Print starts upon key press on Enter. |
| [5.1.3 Print configuration] | Records all system parameters. Print starts upon key press on Enter. |
| [5.1.4 Print PrimeFlow status] | Print status for all computer. Print starts upon key press on Enter. |
| [5.1.5 Print PrimeFlow motor status] | Print status for all motors Print starts upon key press on Enter. |

Two examples of printouts is shown. To the left is a printout of a specific register (menu 5.1.1). To the right is a printout of the configuration (menu 5.1.3).

| **** | ***** |
|---------------------------|----------|
| Serial number | |
| Register | |
| Volume applied: | 332 ga |
| Area: | 4.72 a |
| Travelled spray distance | 0.9 n |
| Start date | 10;13;1 |
| Start time | 11;0 |
| Stop date | 10;13;1 |
| Stop time | 11;4 |
| Time used (spraying time) | (|
| Work rate | 7.19 ac/ |
| Average spray speed | 1.4 mp |
| Max. spray speed | 4.5 mp |
| Average volume rate | 22.8 gp |
| Date printed | 10;13;1 |
| Time printed | 11;5 |
| Notes | |

| HARDI HC6500 - configu ****** | uration |
|--|--|
| Date printed: Time printed: | 10;13;14 3;40 |
| ******* | ***** |
| Terminal Serial number: JobCom Serial number: Terminal SW version: JobCom SW version: Register: Total volume applied: Total area: Tot travel spray distanc: Start date: Start date: Stop date: Stop date: Stop time: Tot time used spray time: Total work rate: Total averag spray speed: Total max. spray speed: Total averag volume rate: | 2011120983 2011114057 3.03 1709.00 1 332 gal 4.72 ac 0.9 mi 10;13;14 11;00 10;13;14 11;47 0 7.19 ac/h 1.4 mph 4.5 mph 22.8 gpa |

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Menu 5.2 Data dump

Enables data dump to an office printer. This could be done for example, by using the HyperTerminal function in Microsoft Windows.

| Menu | Help text |
|--------------------------------------|---|
| [5.2.1 Data dump of raw data] | Transmits data from all 99 registers in comma-separated file for Excel. |
| [5.2.2 Hyperterminal service report] | Transmits to PC at high speed. Show Configuration, Error Log, Track, PrimeFlow. |

For HyperTerminal to communicate properly the COM port settings must be set as shown before transmitting data.

The Hyper Terminal has to be activated on the PC and a communication cable (ref. no. 72271600) must be connected to the COM port:

ISOBUS:

• COM 1 on the SetBox.

| COM1 Properties | | ? 🗙 |
|--------------------------|-------------------|----------|
| Port Settings | | |
| | | |
| <u>B</u> its per second: | 9600 | ~ |
| Data bits: | 8 | |
| <u>_</u> | | |
| Parity: | None | ~ |
| <u>S</u> top bits: | 1 | ~ |
| Elow control: | Hardware | ~ |
| | | |
| | <u>R</u> estore D |)efaults |
| 0 | K Cancel | |

Off-season storage

Storage

When the tractor and sprayer are parked, completely disconnect the power supply to the sprayer. This will stop the system from using power.



ATTENTION! If the light emitting diode on the SetBox or Grip lights or flashes, the system is still powered!

The SetBox and Grip should be protected from moisture and should be removed if the tractor does not have a cabin.

10 - Maintenance

Operational problems

Fault finding the system

When a problem occurs with the system, it is good practice to go through the general fault finding schematic, before contacting your HARDI® dealer.

| Problem | Possible cause | Try/Test | Check/Behavior |
|---|---------------------------|---|--|
| Flow | Is there flow readout? | Select I/min in the system menu. | Does this correspond to actual flow? |
| | | Use test menu. (menu 4.5.1 + 4.5.4.1) | Are there signal from flowmeter? |
| | | Are flow PPU correct? | Max. 10% change from given values. |
| | | Does pressure equalization valves leak? (Not COMMANDER/EFC). | |
| Speed | Is there speed readout? | Use test menu. (menu 4.5.1 4.5.4.1) | Any signal from sensor? |
| | | Check LED diode on sensor. | Sensor at metal = ON , Sensor at hole = OFF . |
| | Is speed stable? | Max. deviation ±0,15 km/h | Distance to wheel speed ring 4-5 mm? |
| | | | Is speed ring buckled? |
| | | | Does sensor sense middle of holes? |
| | | | Does speed ring vibrate when running? |
| Active boom width | Signal received? | Select boom width menu. | Correspond to actual boom width? |
| DynamicFluid4 pressure regulation valve | Does manual control work? | Turn valve to maximum. | Can the valve turn reverse, both at min. and max.? |

Checks for clogging

Clogging of valves and hoses should be avoided. If suspicious of clogging, the following checks are recommended



DANGER! As water will be flushed out, tests are to be done with a clean sprayer in order to avoid spot contamination and risk of personal injury.

| Valve positions | | | | | | |
|-----------------------|------------------------|---------------------|-----------------|----------------------------|--|---|
| Suction SmartValve | Pressure SmartValve | External fill valve | Agitation valve | Pump | Other | Verify |
| External fill | To MainTank | (Open) | Closed | Turned ON | Connect hose from external tank to External fill | Look in MainTank. Check that water exits from ejector |
| From MainTank | Pressure Empty | (Closed) | Closed | Turned ON | | Look in MainTank. Check that safety valve opens |
| From MainTank | Spraying | (Closed) | Closed | Turned ON | Boom sections closed | Look in MainTank. Check that safety valve closes and does not leak water |
| From MainTank | Spraying | (Closed) | Closed | Turned ON | Boom sections closed | Look in MainTank. Check that water exits pressure filter dump line |
| From MainTank | | (Closed) | | Turned ON | | Look in MainTank. Check that water exits from agitation tube |
| From MainTank | | (Closed) | Closed | Turned ON | | Look in MainTank. Check that water exits from thin tube |
| From MainTank | | (Open) | Closed | Turned ON | Close lid on MainTank. Remove cap on External filling coupler | Check that water comes out of External filling coupler |
| From MainTank | | (Closed) | Closed | Turned OFF | Pull the 2 rinsing nozzles up from tank | Check by hand that rinse nozzles can rotate |
| From MainTank | | (Closed) | Closed | Turned ON at low R.P.M. | Start pump, rum at Iow RPM | From tractor cab, confirm water exits rinse nozzles |

Checks for external leak

If suspicious of external leaks:

1. Clean sprayer, if necessary, as water will be flushed out later.



DANGER! As water will be flushed out, test is to be done with a clean sprayer, in order to avoid spot contamination and risk of personal injury.

2. Run a stationary FastFlush, and monitor if water exits sprayer in places other than the boom. In particular monitor area below sprayer frame.

Location of components (trailed sprayers)

A complete list of sensors on HARDI® COMMANDER sprayers. Other models will vary. Some sensors optional, depending on various possible configurations. The function of some sensors can be viewed in menu 4.7 Emergency track Align, others function can be viewed in the submenus of menu 4.5 Test of sensors.



| Sensor number | Description | Sensor number | Description |
|---------------|---------------------------|---------------|----------------------------------|
| 1 | Suction SmartValve | 26 | Boom sensor Right |
| 2 | Pressure SmartValve | 27 | Dynamic sensor |
| 3 | Distribution valves | 28 | PrimeFlow SMCU Left |
| 4 | Pressure control valve | 29 | PrimeFlow step motor Left |
| 5 | Boom flow meter | 30 | PrimeFlow SMCU Right |
| 6 | Boom bypass valve | 31 | PrimeFlow step motor Right |
| 7 | External filling valve | 32 | End nozzle Left |
| 8 | Pressure sensor | 33 | End nozzle Right |
| 9 | Main tank gauge | 34 | TWIN fan speed actuator |
| 10 | AutoAgitation valve | 35 | TWIN angle actuator Left |
| 11 | RinseTank flow meter | 36 | TWIN angle actuator Right |
| 12 | RinseTank full sensor | 37 | TWIN Fan speed sensor |
| 13 | Main tank full sensor | 38 | Middle fold lock sensor Left |
| 14 | Boost line valve | 39 | Middle fold lock sensor Right |
| 15 | Forward speed sensor | 40 | Foam marker compressor |
| 16 | PTO Pump speed sensor | 41 | JobCom |
| 17 | FlexCapacity speed sensor | 42 | DAH PCB |
| 18 | Paralift height sensor | 43 | PrimeFlow step-up transformer |
| 19 | Slant angle sensor | 44 | 9 sec. Central Junction box PCB |
| 20 | Pendulum lock sensor | 45 | 13 sec. Central Junction box PCB |
| 21 | Pendulum un-lock sensor | 46 | PrimeFlow Cent. Junction box PCB |
| 22 | SafeTrack front sensor | 47 | HY Cent. Junction box PCB |
| 23 | SafeTrack rear sensor | 48 | Dilution kit box PCB |
| 24 | SafeTrack lock sensor | 49 | TerraForce HY Junction box PCB |
| 25 | Boom sensor Left | | |

Location of components (self-propelled sprayers)

A complete list of sensors on HARDI® SARITOR sprayers. Other models will vary. Some sensors optional, depending on various possible configurations. The function of some sensors can be viewed in the submenus of menu 4.5 Test of sensors.



| Sensor number | Description |
|---------------|----------------------------|
| 1 | Main tank valve |
| 2 | Flush tank valve |
| 3 | Distribution valves |
| 4 | Boom flow meter |
| 5 | Boom bypass valve |
| 6 | Pressure sensor |
| 7 | Main tank gauge |
| 8 | Main tank full sensor |
| 9 | Hydraulic oil level sensor |
| 10 | Fuel level sensor |
| 11 | Rinse nozzle valve |
| 12 | AutoAgitation valve |
| 13 | Speed sensor |
| 14 | Speed & Temperature sensor |
| 15 | Angle sensor |
| 16 | Work station light switch |
| 17 | Pump speed sensor |
| 18 | Paralift height sensor |
| 19 | Slant angle sensor |
| 20 | Pendulum lock sensor |
| 21 | Pendulum un-lock sensor |

| Sensor number | Description |
|---------------|----------------------------------|
| 22 | Boom sensor Left |
| 23 | Boom sensor Right |
| 24 | Dynamic sensor |
| 25 | PrimeFlow SMCU Left |
| 26 | PrimeFlow step motor Left |
| 27 | PrimeFlow SMCU Right |
| 28 | PrimeFlow step motor Right |
| 29 | End nozzle Left |
| 30 | End nozzle Right |
| 31 | Middle fold lock sensor Left |
| 32 | Middle fold lock sensor Right |
| 33 | Foam marker compressor |
| 34 | JobCom |
| 35 | PCB for external controls |
| 36 | 9 sec. Central Junction box PCB |
| 37 | 13 sec. Central Junction box PCB |
| 38 | PrimeFlow Cent. Junction box PCB |
| 39 | HY Cent. Junction box PCB |
| 40 | TerraForce HY Junction box PCB |
| 41 | External camera |

Fault codes

Under these menus you can check if the communication is ok. This is used both by technicians and skilled operators.

To troubleshoot in field and see if CAN communication works, each computer unit has a LED, which indicates condition and status of this computer.

- It will give out light when the units are turned on.
- If there is an error, a signal will show in a morse code if the CAN connection is damaged to that specific unit.

In the following is a full table of Alarms, Warnings etc. that will or can be shown on Terminal display.

NOTE! These are useful for service staff:
 ID is the fault identifier and is the number shown in the display.
 Pr is alert priority.

| ID | Туре | Text at display detail | Criteria for fault Operations disabled | Full screen Help text | Pr |
|----|-------|---------------------------------|---|--|----|
| 01 | Alarm | Sensor 12V supply failure | While the short circuit is present. SafeTrack shifted to manual. Auto is disabled. | Sensor 12V supply failure | 1 |
| 02 | Alarm | Sensor 5V supply failure | While the short circuit is present. SafeTrack shifted to manual. Auto is disabled. | Sensor 5V supply failure | 2 |
| 03 | Alarm | Track Lock sensor failure | Sensor signal is less than 0.5V. | Track Lock sensor failure. | 3 |
| | | | All SafeTrack keys are disabled. | All SafeTrack keys are disabled. | |
| | | | Manual tracking, "Align" and "Boom fold inner in" is only possible from menu 4.7. | Manual tracking, "Align" and "Boom fold inner in" is only possible from menu 4.7. | |
| 04 | Alarm | Trapeze lock locked illegally | Lock is detected locked unintentionally. | Lock is detected released unintentionally. | 4 |
| | | | All SafeTrack keys are disabled. | Missing hydraulic pressure on lock cylinder. Mis adjusted lock sensor. | |
| | | | only possible from menu 4.7. | Manual tracking, "Align" and "Boom fold inner in" is only possible from menu 4.7. | |
| 05 | Alarm | Trapeze lock not locking | Attempt to lock, but no "lock" signal on sensor input. | Attempt to lock, but no "lock" signal on sensor input. | 12 |
| | | | All SafeTrack keys are disabled. Manual tracking, "Align" and "Boom fold inner in" is only possible from menu 4.7 | Lock sensor mis adjusted. Mechanical defect prevents lock to penetrate hole. Mis adjusted rear angle sensor. | |
| | | | | Manual tracking, "Align" and "Boom fold inner in" is only possible from menu 4.7. | |
| 06 | Alarm | Trapeze lock released illegally | Lock is detected released unintentionally. | Lock is detected released unintentionally. | 13 |
| | | | All SafeTrack keys are disabled. | Poor lock sensor adjustment. Lock cylinder fallen off. | |
| | | | only possible from menu 4.7. | Manual tracking, "Align" and "Boom fold inner in" is only possible from menu 4.7. | |
| 07 | Alarm | Trapeze lock not released | When pressing auto to release lock but no "release" | Trapeze lock not released. | 14 |
| | | | signal from lock sensor. Auto and manual are disabled. | Attempt to release lock, but no "release" signal from lock sensor. | |
| | | | | No hydraulic pressure. Mis adjusted lock sensor. | |
| | | | | Mechanical defect. | |
| 08 | Alarm | Track Boom sensor failure | The boom sensor signal is less than 0.5V. | Track Boom sensor failure. | 15 |
| | | | The boom sensor changes state, without "Boom fold inner" button is active. | Automatic and manual tracking is aborted. Only "Align" function is possible | |
| | | | Auto and Manual is disabled. | | |
| | | | Only "Align" function is possible. | | |

| ID | Туре | Text at display detail | Criteria for fault | Full screen Help text | Pr |
|----|---------|------------------------------|--|---|----|
| | | | Operations disabled | | |
| 09 | Alarm | Track Front sensor failure | The alarm is generated, if the sensor signal is less than 0.2V or exceeds 4.8V | Track front sensor failing. | 16 |
| | | | Automatic tracking is aborted until the system has | Automatic tracking is aborted. Manual tracking and "Align" function is possible. | |
| | | | SafeTrack shifted to manual. | Pressing "Enter will remove the alarm from the | |
| | | | Auto is disabled. | display until the system has been repooted. | |
| 10 | Alarm | Track Rear sensor failure | The alarm is generated, if the sensor signal is less | Track Rear sensor failure | 17 |
| 10 | / tarri | index riedi Serisor idildire | than 0.5V or exceeds 4.5V. | Automatic tracking is aborted until the system has | 17 |
| | | | SafeTrack shifted to manual. | been rebooted. | |
| | | | Auto and Align is disabled. | If "Align" mode is selected, no movement takes | |
| | | | | Manual tracking still possible. | |
| 11 | Alarm | Agitation valve fault | Error detection not active, profet error detection | Agitation valve fault. Motor disconnected. Motor | 18 |
| | | | not used. | short circuit or blocked. Sensor failing. | |
| | | | On fault following occurs: | | |
| | | | Autoviash disabled | | |
| | | | Used by Autowash/AutoFill | | |
| 12 | Alarm | Reserved | Reserved replaced by ID154-159 | Fill valve fault. Motor disconnected. Motor short | 19 |
| | / tarri | heserved | Error detection not active, profet error detection | circuit or blocked. Sensor failing. | 12 |
| | | | not used. | | |
| | | | On fault following occurs: | | |
| | | | AutoWash allowed | | |
| | | | AutoFill disabled | | |
| | | | Clear alarm by reboot | | |
| | A. | Eluid austana fault | | Ille and Annual a state state in Constitution from a state | 20 |
| 13 | Alarm | Fluid system fault | When suction SmartValve is on other port than RinseTank and RinseTank flow exceed 10 l/min. | RinseTank line. | 20 |
| | | | On fault following occurs: | | |
| | | | AutoWash disabled. | | |
| | | | AutoFill disabled. | | |
| | | | Used by Autowash/AutoFill | | |
| 14 | Alarm | m No RinseTank flow | Error detection. | RinseTank empty or no rinse water flow due to | 21 |
| | | | On fault following occurs: | other reasons. | |
| | | | AutoWash disabled. | | |
| | | | Autorial allowed. Clear alarm by RinseTank full switch or flow from | | |
| | | | RinseTank | | |
| | | | Used by Autowash/AutoFill | | |
| 15 | Alarm | Reserved | Reserved, replaced by ID154-159 | PressureValve fault. Motor disconnected. Motor | 22 |
| | | | Error detection not active, profet error detection not used. | short circuit or blocked. Sensor failing. | |
| | | | On fault following occurs: | | |
| | | | AutoWash disabled | | |
| | | | AutoFill disabled | | |
| | | | Used by Autowash/AutoFill | | |
| 16 | Alarm | Reserved | Reserved, replaced by ID141-145 | Regulation valve fault. Motor disconnected. Motor | 23 |
| | | | Error detection not active, profet error detection | snort circuit or blocked. Sensor failing. | |
| | | | not used. On fault following occurs: | | |
| | | | AutoWash disabled | | |
| | | | AutoFill allowed | | |
| | | | Used by Autowash/AutoFill | | |

| ID | Туре | Text at display detail | Criteria for fault | Full screen Help text | Pr |
|----|-------------------|--------------------------------|--|--|----|
| 17 | Alarm | Reserved | Reserved, replaced by ID154-159 Error detection not active, profet error detection not used. On fault following occurs: AutoWash disabled AutoFill disabled Used by Autowash/AutoFill | SuctionValve fault. Motor disconnected. Motor short circuited or blocked. Sensor failing. | 24 |
| 18 | Alarm | TankGauge fault | When TankGauge is enabled and frequency is below 50Hz. AutoWash is disabled. AutoFill is disabled. Used by Autowash/AutoFill | TankGauge fault. TankGauge frequency is detected below 50Hz. | 25 |
| 19 | Warning | Software error Terminal | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 26 |
| 20 | Warning | Software error JobCom | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 27 |
| 21 | Warning | Software error Grip | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 28 |
| 22 | Warning | Software error SetBox | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 29 |
| 23 | Warning | Software error FluidBox | | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 30 |
| 24 | Warning | CAN bus failing to JobCom | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 31 |
| 25 | Warning | CAN bus failing to SetBox | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 32 |
| 26 | Warning | CAN bus failing to Grip | Close hydraulic valves | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 33 |
| 27 | Warning | CAN bus failing to FluidBox | | Turn off PTO to stop spray. Turn off power to stop hydraulics. | 34 |
| 28 | Illegal action | Track Boom fold. Align sprayer | User starts to fold the boom, and the sprayer trapeze is not locked. BoomFoldInner is disabled. | Track Boom fold Align sprayer. The alarm is present while the sprayer is not locked, and a "fold inner" button is pressed. No folding takes place. | 38 |
| 29 | Illegal action | Track unfold Boom | Alarm for attempt to switch to "Manual" or "Auto" mode in a situation where boom is not detected unfolded. When the boom is detected unfolded the trapeze lock is unlocked and the message disappears. Auto and manual is disabled. | Track unfold Boom. Alarm for attempt to switch to "Manual" or "Auto" mode in a situation where boom is not detected unfolded. Unfold the boom. In half steer mode: Risk of bending folded side. Contact service. | 39 |
| 30 | Illegal action | Main on/off is on | When pressing softkey for BoomFlush, FastFlush, MultiRinse while Main on off is on. Keypress does not start process. Used by Autowash/AutoFill | Main on off is on. Turn Main ON OFF to off before starting AutoWash | 40 |
| 31 | Illegal action | MainTank not empty | When pressing softkey for BoomFlush, FastFlush, MultiRinse while MainTank is not empty. Keypress does not start process. Used by Autowash/AutoFill | MainTank not empty. AutoWash cannot be started. | 41 |
| 32 | Illegal action | No rinse water | When pressing softkey for either BoomFlush, FastFlush, MultiRinse while RinseTank is calculated too empty for that program. Keypress does not start process. Used by Autowash/AutoFill | Not enough rinse water for selected program. AutoWash cannot be started. | 42 |

| ID | Туре | Text at display detail | Criteria for fault | Full screen Help text | Pr |
|----|---------|----------------------------|---|---|----|
| | | | Operations disabled | | |
| 33 | Illegal | Steering not active - Over | When speed is too high for steering (SafeTrack ESP) | . Speed too high for steering - slow down! | 43 |
| | action | speeding: | SafeTrack is disabled. Steering is enabled upon keypress SafeTrack auto. | | |
| 34 | Waiting | Start pump 2 | Valves are positioned as in AutoWash table. | Double pump must be started to flush hoses. | 44 |
| | | | After press on softkey computer continues to next step. | Stop and start Double pump with hydraulic lever, as Warning prompts you to. | 5 |
| | | | See also screen layouts. | | |
| | | | Used by Autowash/AutoFill | | |
| 35 | Waiting | Stop pump 2 | Valves are positioned as in AutoWash table. | Double pump must be stopped to avoid chemical in boom. | 45 |
| | | | After press on softkey computer continues to next step. See also screen layouts. | Stop and start Double pump with hydraulic lever, as | ò |
| 36 | Waiting | Pause | Used by Autowash/AutoFill Upon press of softkey or low or high PTO pump | AutoWash is paused by keypress. | 46 |
| | | | RPM or Flexcap RPM | | |
| | | | See also screen layouts Used by Autowash/AutoFill | | |
| 37 | Warning | PrimeFlow Comm fault | | Communication to PrimeFlow SMCU's are failing. Fault is probably due to broken cable or bad connectors for power or data. | 47 |
| 38 | Warning | Output failing to sect 1 | Detected by H-bridge on I2C bus | Output failing to sect 1 | 48 |
| 39 | Warning | Output failing to sect 2 | Detected by H-bridge on I2C bus | Output failing to sect 2 | 49 |
| 40 | Warning | Output failing to sect 3 | Detected by H-bridge on I2C bus | Output failing to sect 3 | 50 |
| 41 | Warning | Output failing to sect 4 | Detected by H-bridge on I2C bus | Output failing to sect 4 | 51 |
| 42 | Warning | Output failing to sect 5 | Detected by H-bridge on I2C bus | Output failing to sect 5 | 52 |
| 43 | Warning | Output failing to sect 6 | Detected by H-bridge on I2C bus | Output failing to sect 6 | 53 |
| 44 | Warning | Output failing to sect 7 | Detected by H-bridge on I2C bus | Output failing to sect 7 | 54 |
| 45 | Warning | Output failing to sect 8 | Detected by H-bridge on I2C bus | Output failing to sect 8 | 55 |
| 46 | Warning | Output failing to sect 9 | Detected by H-bridge on I2C bus | Output failing to sect 9 | 56 |
| 47 | Warning | Output failing to sect 10 | Detected by H-bridge on I2C bus | Output failing to sect 10 | 57 |
| 48 | Warning | Output failing to sect 11 | Detected by H-bridge on I2C bus | Output failing to sect 11 | 58 |
| 49 | Warning | Output failing to sect 12 | Detected by H-bridge on I2C bus | Output failing to sect 12 | 59 |
| 50 | Warning | Output failing to sect 13 | Detected by H-bridge on I2C bus | Output failing to sect 13 | 60 |
| 51 | Warning | Output failing to bypass | | | 61 |
| 52 | Warning | Electronic fuse 1 is on | Voltage drop over electrothermal fuse | | 62 |
| 53 | Warning | Electronic fuse 2 is on | Voltage drop over electrothermal fuse | | 63 |
| 54 | Warning | Electronic fuse 3 is on | Voltage drop over electrothermal fuse | | 64 |
| 55 | Warning | Electronic fuse 4 is on | Voltage drop over electrothermal fuse | | 65 |
| 56 | Warning | RinseTank not full | When main tank has been filled and rinse tank is empty | . Remember to re-fill rinse tank. | 66 |
| 57 | Warning | Main tank nearly empty | Main tank empty (tank gauge value set in menu 2.5.2). | Main tank is nearly empty. Consider distance left before leaving field. | 67 |
| 58 | Warning | Sections OFF | If main ON/OFF is switched ON and one or more sections are OFF. | Note that one or more sections are switched OFF. | 68 |
| 59 | Warning | Spray pressure too high | Spray pressure too high (limit set in menu 2.5.3.1). | Decrease speed or change to nozzles with larger capacity. | 69 |
| 60 | Warning | Spray pressure too low | Spray pressure too low (limit set in menu 2.5.3.2). | Change to nozzles of less capacity or increase speed if safe. | 70 |

| ID | Туре | Text at display detail | Criteria for fault Operations disabled | Full screen Help text | Pr |
|-----|-----------|---|--|--|-----|
| 61 | Warning | Speed too high | Speed too high (limit set in menu 2.5.5.1). | Decrease speed. Pressure will be too high. | 71 |
| 62 | Warning | Speed too low | Speed too low (limit set in menu 2.5.5.2). | Increase speed if safe. Pressure will be too low. | 72 |
| 63 | Warning | Appl. volume too high | Application volume too high (% limit set in menu). | Increase speed if safe or change nozzle size.Check regulation valve hoses and filters. | 73 |
| 64 | Warning | Appl. volume too low | Application volume too low (% limit set in menu). | Decrease speed or change nozzle size. Check regulation valve. | 74 |
| 65 | Warning | Fan speed too high | Fan speed too high (limit set in menu 2.5.4.1). | Reduce fan speed | 75 |
| 66 | Warning | Fan speed too low | Fan speed too low (limit set in menu 2.5.4.2). | Increase fan speed | 76 |
| 67 | Warning | PTO speed too low | PTO rev. too low (limit set in menu). | Increase PTO speed | 77 |
| 68 | Warning | PTO speed too high | PTO rev. too high (limit set in menu). | Decrease PTO speed | 78 |
| 69 | Warning | Ladder not up | | Raise ladder, to avoid damage to ladder or crop. | 79 |
| 70 | Warning | Wind Speed too high | Wind Speed too high (limit set in menu). | Stop spraying or consider other nozzle types like HARDI® LowDrift. | 80 |
| 71 | Warning | | | | 81 |
| 72 | Warning | | | | 82 |
| 73 | Warning | | | | 83 |
| 74 | Warning | | | | 84 |
| 75 | Warning | Opt. sensor 1 too high | Limit set in menu. | This will be help text | 85 |
| 76 | Warning | Opt. sensor 1 too low | Limit set in menu. | This will be help text | 86 |
| 77 | Warning | Opt. sensor 2 too high | Limit set in menu. | This will be help text | 87 |
| 78 | Warning | Opt. sensor 2 too low | Limit set in menu. | This will be help text | 88 |
| 79 | Warning | Opt. sensor 3 too high | Limit set in menu. | This will be help text | 89 |
| 80 | Warning | Opt. sensor 3 too low | Limit set in menu. | This will be help text | 90 |
| 81 | Warning | Opt. sensor 4 too high | Limit set in menu. | This will be help text | 91 |
| 82 | Warning | Opt. sensor 4 too low | Limit set in menu. | This will be help text | 92 |
| 83 | Reminder | Aborted by keypress | Upon press of softkey | AutoWash is Aborted by keypress. | 93 |
| | | | Used by Autowash/AutoFill | | |
| 84 | Reminder | Aborted by exception # | Aborted by exception, then show number from AW source code | ' AutoWash is completed | 94 |
| 0.5 | Densinden | Fact Fillen and a later brief of a factor | | A set A standing control on the state for state on a set of | 0.5 |
| 85 | Keminder | FastFiller valve high friction | After valve self test | AutoAgitation valve has high friction or poor cabling. Valve will fail within some time. Arrange repair. | 95 |
| 86 | Reminder | Pressure Valve high friction | After valve self test | PressureValve has high friction or poor cabling. Valve will fail within some time. Arrange repair. | 96 |
| 87 | Reminder | Suction Valve high friction | After valve self test | SuctionValve has high friction or poor cabling. Valve will fail within some time. Arrange repair. | 97 |
| 88 | Reminder | Check filters and brakes | Periodically, period defined in extended menu. (Only checked at power up) | It is now time to check the suction and pressure filters. | 98 |
| | | | | The Cyclone pressure filter is hidden under the grey right-hand cowling at the front of the sprayer. | 1 |
| | | | | Check line and nozzle filters too. Check brakes. | |
| 89 | Reminder | Grease boom and track | Periodically, period defined in extended menu. | The boom now needs to be lubricated. | 99 |
| | | | (Only checked at power up) | Yellow labels indicate lubrication points other-wise see operators manual. | : |

| ID | Туре | Text at display detail | Criteria for fault Operations disabled | Full screen Help text | Pr |
|-----|---|---|---|--|-----|
| 90 | Reminder | Grease misc. | Periodically, period defined in extended menu. (Only checked at power up) | The track system now needs to be lubricated. Yellow labels indicate lubrication points otherwise see operators' manual. | 100 |
| 91 | Reminder | Miscellaneous service | Periodically, period defined in extended menu. (Only checked at power up) | See operators' manual for specific sprayer service. | 101 |
| 92 | Reminder | Check nozzles | Periodically, period defined in extended menu. (Only checked at power up) | You need to check the individual nozzle flow per minute. | 102 |
| | | | | A stopwatch and good quality measuring jug is needed. | |
| | | | | Do the test with clean water. | |
| | | | | Nozzles with over 10% of rated new capacity must be discarded. | |
| 93 | Reminder | Stop watch is zero | | Stop watch is zero | 103 |
| 94 | Changed | Track in manual | | Operator has put Track in manual | 104 |
| 95 | Changed | Track in auto | | Operator has put Track in auto | 105 |
| 96 | Changed | Track is locked | | Operator has locked Track | 106 |
| 97 | Changed | Reversing | | Operator is reversing | 107 |
| 98 | Changed | Track unlocked | | Lock is detected released. Hydraulic pressure established. Mis adjusted lock sensor. | 108 |
| 99 | Alarm | PrimeFlow data cable weakness | JobCom does not receive the data it sends. Shift the relay to Full duplex (transmit to both ends) | PrimeFlow bus cable fault is detected. . A failure handling circuit is enabled. | 35 |
| | | | Data cable defect is only detected at Half duplex (listen only right end). | PrimeFlow is in full operation. | |
| | | | No further Data cable defect are detected at Full duplex (transmit to both ends). | | |
| 100 | Alarm | Low PrimeFlow voltage | JobCom measure PrimeFlow supply voltage after fuse for left and right boom part at AI11 and AI12. | A fuse is open or too many rapid shifts on and off of sections has drained the power supply. | 36 |
| | | | Alarm occur when voltage is below 14 volts. | | |
| 101 | Warning | arning PrimeFlow power cable defect | Low power warning from SMCU, when supply is re- established. | Poor power wiring to PrimeFlow computers. One of the 2 power lines are disconnected or connectors | 109 |
| | First low power warning received after power up of are corroded and gives hig system is not valid. | are corroded and gives high resistance. | | | |
| | | | First low power warning received after "Low voltage on supercap" is not valid. | | |
| 102 | Warning | PrimeFlow computer defect | SMCU does not reply on status. | Internal fault in PrimeFlow computer. Can also be | 110 |
| | | | No status request while "Low voltage on supercap" occurs. | caused by 2 of more defects in Primeriow data cable. Check for PrimeFlow data cable weakness. | |
| 103 | Warning | Fold with unlocked pendulum | When pressing FoldCenterIn, FoldLeftIn or FoldRightIn and pendulum is unlocked. | Fold with unlocked pendulum. | 111 |
| 104 | Warning | Boom wing loose | Buttons FoldLeftIn or FoldRightIn are not pressed but the 4 sensors on outer boom wings change from "In spray" to "Not in spray" respectively when they change from "In transport" to "Not in transport". | Boom wing loose. | 112 |
| 105 | Changed | Agitation in Auto | Forward speed > 0.5 km/h and Main On/Off = On | Agitation in Auto | 113 |
| 106 | Warning | Regulation valve in end-stop | Warning appears when pressure regulation algoritm tries to close Regulation valve to increase pressure, but encoder does not give any signals, as micro switch has turned of motor. | JobCom detected that pressure regulation valve does not turn and cannot close and increase pressure and flow any further. Increase PTO RPM. | 114 |
| | | | Alarm should not appear at self test at start up. | Review flow used for agitation. | |
| | | | Pressure regulation is unchanged. | Check for internal leakages. | |

| ID | Туре | Text at display detail | Criteria for fault Operations disabled | Full screen Help text | Pr |
|--|---|---|--|---|-----|
| 107 | Alarm | Slant angle sensor fault | Alarm is active when 2.2.4.3 Slant mirror is enabled and/or if 2.2.4.4 Slant in steps is enabled. | Check sensor and cable on pendulum. Disable HeadLandAssist. | 115 |
| | | | The alarm is generated, if the sensor signal is less than 0.2 Volt or exceeds 4.8 Volt. | Disable Slant in steps. | |
| 108 | Alarm | Boom height sensor fault | Alarm is active when 2.2.4.2 Boom height at headlands is enabled. | | 116 |
| | | | The alarm is generated, if the sensor signal is less than 0.2 Volt or exceeds 4.8 Volt. | | |
| 109 | Alarm | Pressure sensor alarm | Alarm is active when Menu E8.1.7.1 is "Active" | Check connection to boom pressure sensor at | 117 |
| | | | The alarm is generated, if the sensor signal on Al26 (J10_33, J11_33) is less than 3mA or exceeds 21mA | distribution valve junction box. | |
| 110 | Alarm | JobCom Resetting | | Refer to HC 6500 service manual. | 124 |
| 111 | Alarm | JobCom Resetting Done | | Refer to HC 6500 service manual. | 125 |
| 112 | Changed | Flat 1 Level 1 | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7, the setbox TWIN | Defines current Dynamic center setting for the TERRA FORCE boom. | 118 |
| | | Hilly 5 | buttons are dedicated to select the Dynamic center setting. The information pops up when a button | Flat means the boom is free hanging. | |
| | | | has been pushed. | Hilly means the boom will follow the sprayer movements. | |
| 113 | Changed | Changed Flat 1 Level 2 | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7, the setbox TWIN buttons are dedicated to select the Dynamic center setting. The information pops up when a button | Defines current Dynamic center setting for the TERRA FORCE boom. | 119 |
| | | Hilly 5 | | Flat means the boom is free hanging. | |
| | | | has been pushed. | Hilly means the boom will follow the sprayer movements. | |
| 114 | Changed | Flat 1 | When TERRA FORCE boom hydraulics set-up has | Defines current Dynamic center setting for the | 120 |
| | | Level 3 | buttons are dedicated to select the Dynamic center | FERRA FORCE boom. | |
| hilly 5 setting. The information pops up when a but has been pushed. | setting. The information pops up when a button has been pushed. | Hilly means the boom will follow the sprayer movements. | | | |
| 115 | 5 Changed Flat 1 When TERRA Level 4 been selected Hilly 5 setting. The has been pu | Flat 1 Level 4 | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7, the setbox TWIN buttons are dedicated to select the Dynamic center setting. The information poos up when a button | Defines current Dynamic center setting for the TERRA FORCE boom. | 121 |
| | | Hilly 5 | | Flat means the boom is free hanging. | |
| | | has been pushed. | Hilly means the boom will follow the sprayer movements. | | |
| 116 | Changed | Flat 1 Level 5 | at 1 When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7, the setbox TWIN | Defines current Dynamic center setting for the TERRA FORCE boom. | 122 |
| | | Hilly 5 | buttons are dedicated to select the Dynamic center setting. The information pops up when a button | Flat means the boom is free hanging. | |
| | | | has been pushed. | Hilly means the boom will follow the sprayer movements. | |
| 117 | Warning | D-center incorrect position | Time-out on sensor signal Al25. | Attempt to move Dynamic center cylinder did not | 37 |
| | | | TERRA FORCE boom hydraulics set-up has been selected in menu F8.6.3.7 | succeed within the given time frame. | |
| | | | Buttons has been activated to move the Dynamic center. | Check Dynamic center position sensor. | |
| | | | The selected setting has not been reached within 10 seconds. | | |
| | | | Reset by keypress "enter" or attempt to move Dynamic center. | | |
| 118 | Warning | Pendulum locking failed. | Time-out on sensor signal Al1 when attempting to lock. | Attempt to move Pendulum lock cylinder did not succeed within the given time frame. | 5 |
| | | | See table "TerraForce Pendulum lock" in terminal specification xxxx | Check the hydraulics connections and pressure. Check Pendulum lock position sensor adjustment. | |
| | | | Reset by attempt to lock. | | |

| ID | Туре | Text at display detail | Criteria for fault | Full screen Help text | Pr |
|-----|-------------------|--|---|--|-----|
| 110 | Marciaa | Dan dulum valance failed | | Dendulum is lacked unintentionally. The | 6 |
| 119 | warning | Pendulum release falled. | attempting to unlock. | suspension will be damaged. | 0 |
| | | | See table "TerraForce Pendulum lock" in terminal specification xxxx | Check the hydraulics connections and pressure. | |
| | | | Reset by attempt to release. | Check Pendulum lock position sensor adjustment. | |
| 120 | Warning | STOP! PENDULUM LOCKED! | Time-out on sensor signal Al1 (E0.7.4 setting) when attempting to unlock and speed >E0.7.2 setting. See table "TerraForce Pendulum lock" in terminal | Pendulum is locked unintentionally when attempting to spray. The suspension will be damaged. | 7 |
| | | | specification ver 35 | Check the hydraulics connections and pressure. | |
| | | | Reset by removal of coarse (either unlock succeeded or speed <e0.7.2).< td=""><td>Check Pendulum lock position sensor adjustment.</td><td></td></e0.7.2).<> | Check Pendulum lock position sensor adjustment. | |
| 121 | Alarm | Pendulum lock sensor. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7 | No or wrong signal from sensor. Shorted or disconnected. | 8 |
| | | | The alarm is generated: | Check Pendulum lock sensor adjustment and/or | |
| | | | • if the sensor signal on Al1 is less than 0,5V. | connection. | |
| | | | Illegal transition. See table "lerra-Force Pendulum lock" in terminal specification ver 35 | | |
| 122 | Warning | Dynamic Center sensor. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7 | Signal from sensor out of range. Shorted or disconnected. | 11 |
| | | | The alarm is generated, if the sensor signal on AI25 is less than 0,2V or exceeds 4,8V. | Check Dynamic center position sensor adjustment and/or connection. | |
| | | | Reset by keypress "enter". | | |
| 123 | Warning | Folding not allowed. | Attempt to fold when speed >E0.7.2 km/h. Folding blocked. | It is not allowed to fold or unfold the boom while driving. Stop the vehicle. | 123 |
| | | | Reset when speed <e0.7.2 are="" buttons="" fold="" h="" km="" or="" released.<="" td="" when=""><td></td><td></td></e0.7.2> | | |
| 124 | Reminder | ISObus terminal recovered | | | 126 |
| 125 | Reminder | ISObus bridge recovered | | | 127 |
| 126 | Reminder | No Dilution | Appears when dilution kit function is activated, and no outputs are active. | Fluid systems works normally. | 128 |
| 127 | Reminder | Tank Dilution | Appears when dilution kit function is activated, and tank output is active. | Suction from rinse tank. Flush tank through tank cleaning nozzles. | 129 |
| 128 | Reminder | Boom Dilution | Appears when dilution kit function is activated, and | Suction from rinse tank. | 130 |
| | | | Boom output is active. | If nozzles are open - flush feed hoses. | |
| | | | | If nozzles are closed - flush dump hose. | |
| 129 | Warning | Pump over speeding | Pump RPM exceed 5000 RPM. | Pump RPM exceed manufacturer's limitation. | 131 |
| 130 | Warning | Vehicle over speeding | Forward speed exceed setting in E0 menu, and MainFlowOnOff is on. | Vehicle over speeding while spraying. | 132 |
| 131 | Warning | Boom not in transport. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7+8 | Place boom in transport position before driving. Check transport lock function. | 10 |
| | | | The alarm is generated, if an attempt to bring the boom into transport position failed, or if the user forgot to bring it there. | Check boom height sensor. | |
| 132 | Illegal action | One function only! | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7+8 | It is not allowed to use multiple folding buttons/ functions simultaneously. | 133 |
| | | | Appears on TERRA FORCE booms when the user tries to us more than one function at a time. | | |
| 133 | Illegal action | Unfold inner wing. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7+8. | Do not attempt to fold outer wings, if inner wing is not fully unfolded. | 134 |
| | | | Wrong folding sequence. | | |
| 134 | Illegal action | Keep folding 1 st outer wing. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7+8. Wrong folding sequence. | Finish the folding of 1 st outer wing. | 135 |

| ID | Туре | Text at display detail | Criteria for fault Operations disabled | Full screen Help text | Pr |
|-----|-------------------|--|--|--|-----|
| 135 | Illegal action | Keep folding 2 nd outer wing. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7+8. Wrong folding sequence. | Finish the folding of 2 nd outer wing. | 136 |
| 136 | Warning | Lift the boom. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7+8. | The boom lift position is too low to ensure proper function of the transport lock. | 137 |
| | | | The boom lift position is too low to ensure proper function of the transport lock. | | |
| 137 | Warning | Boom not in transport. | See state machine table "TERRA FORCE transport lock and suspension relief". | Place the boom correctly in transport position before driving. Check transport lock function. Check boom height sensor. | 138 |
| 138 | Reminder | Mismatch Box and setup. | When setup in E8.5.8 Grip, SetBox, armrest does not match jumper positions in SetBox PCB for armrest and Outside switches. | Setup in E8.5.8 Grip, SetBox, armrest does not match jumper positions in SetBox PCB for armrest and Outside switches. | 139 |
| | | | Reminder is not sent when boxes are not connected or software has no jumper positions PG | | |
| 139 | Alarm | Dynamic center sensor. | When dynamic center function is enabled in menu E.8.6.7 | | 139 |
| 140 | Alarm | Pendulum unlock sensor. | When TERRA FORCE boom hydraulics set-up has been selected in menu E8.6.3.7 | No or wrong signal from sensor. Shorted or disconnected. | 9 |
| | | | The alarm is generated: • if the sensor signal on AI5 is less than 0,5V. | Check Pendulum unlock sensor adjustment and/or connection. | |
| | | | Illegal transition. See table "TerraForce Pendulum lock" in terminal specification ver 53 | | |
| 141 | Warning | Reg. Valve sensor fault. | | | 140 |
| 142 | Warning | Boom flow sensor fault. | | | 141 |
| 143 | Warning | Boom press sensor fault. | | | 142 |
| 144 | Warning | Pump sensor fault. | Used by Autowash/AutoFill | | 143 |
| 145 | Warning | Reg. Valve motor fault. | | | 144 |
| 146 | Warning | Agitation sensor fault | Not used 11 Alarm Agitation valve fault is used instead | | 145 |
| 147 | Warning | Agitation motor fault | Not used 11 Alarm Agitation valve fault is used instead | | 146 |
| 148 | Warning | Centrifugal valve calib failed | When Regulation SW cannot detect and calculate X axis crossing or slope of hydraulic valve characteristic Used by Regulation | | |
| 149 | Warning | Stack overflow | | | 148 |
| 150 | Warning | PF motor blocked #xxx | PrimeFlow. When command 09h is "Status advanced" is read, each motor can be detected blocked, shorted or disconnected. The "#xxx" indicates the actual nozzle number. | A PrimeFlow motor is detected blocked. Inspect motor and nozzle condition. Clean or replace valve if necessary. | 149 |
| 151 | Warning | PF motor short #xxx | PrimeFlow. When command 09h is "Status advanced" is read, each motor can be detected blocked, shorted or disconnected. The "#xxx" indicates the actual pozzle number | A PrimeFlow motor is detected shorted. Inspect motor and connector condition. | 150 |
| 152 | Warning | PF motor disconnect #xxx | PrimeFlow. When command 09h is "Status advanced" is read, each motor can be detected blocked, shorted or disconnected. The "#xxx" indicates the actual nozzle number. | A PrimeFlow motor is detected disconnected. Inspect motor, SMCU and connector condition. | 151 |

| ID | Туре | Text at display detail | Criteria for fault Operations disabled | Full screen Help text | Pr |
|-----|----------|-------------------------------|---|---|----|
| 153 | Reminder | AutoWash completed xx cycles | When program is completed Used by Autowash/AutoFill | AutoWash is completed AUTOWASH_CYCLE_COMPLITED | |
| 154 | Warning | FastFiller valve motor fault | Sensor does not change 0.5 volt when motor is activated for 1 sec Or Valve do not get into position within 4 sec Or verify speed 50 mV /100 msec Beware of blind zone See also alert ID13 Used by Autowash/AutoFill | FAST_FILL_VALVE_MOT_FAULT | |
| 155 | Warning | FastFiller valve sensor fault | Sensor changes more than 100 mV when motor is not activated Or Speed below 50 mV /100 msec Used by Autowash/AutoFill | FAST_FILL_VALVE_SENS_FAULT | |
| 156 | Warning | PressureValve motor fault | Sensor does not change when motor is activated Used by Autowash/AutoFill | PRESSURE_VALVE_MOT_FAULT | |
| 157 | Warning | PressureValve sensor fault | Sensor changes when motor is not activated Used by Autowash/AutoFill | PRESSURE_VALVE_SENS_FAULT | |
| 158 | Warning | SuctionValve motor fault | Sensor does not change when motor is activated Used by Autowash/AutoFill | SUCTION_VALVE_MOT_FAULT | |
| 159 | Warning | Suction Valve sensor fault | Sensor changes when motor is not activated Used by Autowash/AutoFill | SUCTION_VALVE_SENS_FAULT | |
| 160 | Alarm | Illegal AutoWash Setup | Illegal pumps chosen Autowash will not start (preconditions not fulfilled) Used by Autowash/AutoFill | ILLEGAL_AWASH_SETUP | |
| 161 | Warning | Pump RPM too low Increase | Pump RPM is below table limits Increase to go to Pause Used by Autowash/AutoFill | PUMP_RPM_TOO_LOW | |
| 162 | Warning | Pump RPM too high Decrease | Pump RPM is above table limits Decrease to go to Pause Used by Autowash/AutoFill | PUMP_RPM_TOO_HIGH | |
| 163 | Warning | Increase pump flow | With EFC or PrimeFlow: When valve is closed and regulator is in state 6x With EVC: When valve is in closed end stop and flow is over threshold Used by Regulation | INC_PUMP_FLOW, | |
| 164 | Warning | Reduce pump flow | With EFC or PrimeFlow: When valve is open and regulator is in state 6x With EVC: When valve is in open end stop and flow is over threshold Used by Regulation | RED_PUMP_FLOW, | |
| 165 | Warning | Jobcom Fram defect | Write data to FRAM then read If read data is different from write data Clear alarm by power off p power on | | |

Emergency operation

In an emergency situation

If an error occurs in the system then choose Computer CAN status. This test will show if there is communication between the units. The menu will be as shown.



ATTENTION! See also "Menu 4.7 Emergency" on page 8.3.



Operation when a sensor fails

When one of the sensors for RPM, flow or pressure fails, the system will work in a limp home mode with reduced, though acceptable, performance. One of the alarm ID's between 140 to 147 will be triggered in the controller display. See also "Fault codes" on page 11.5.

- In the auto mode, the system will not work with 2 failing sensors, hence the operator should repair the failing sensor as soon as possible.
- The pressure regulation can use both wheel speed sensor on trailer and GPS speed via ISOBUS.



NOTE! SafeTrack only works with wheel speed sensor.

Pressure regulation angle sensor works both as a feed back to the computer and as the end stop switch. If angle sensor fails, the operator can continue turning regulation valve past the completely closed position.

Failure in the sensors below will cause an inaccurate calculation of the volume rate when spraying. In order to be able to end a spray job when a sensor fails, do the following:

| RPM | Flow | Pressure | Speed | Valve angle | Mode for regulation | Extra actions for operator |
|--------|--------|----------|--------|-------------|--|---|
| Use | Use | Use | Use | Use | Full performance | None |
| Defect | Use | Use | Use | Use | Reduced performance | None |
| Ignore | Defect | Use | Use | Use | Reduced performance | Setup new size when changing nozzle, see "Menu 3.4.3 Nozzle size flow at 45 psi" on page 7.10. |
| Defect | Defect | Use | Use | Use | Reduced performance | Setup new size when changing nozzle, see "Menu 3.4.3 Nozzle size flow at 45 psi" on page 7.10. |
| Ignore | Use | Defect | Use | Use | Reduced performance | Setup new size when changing nozzle, see "Menu 3.4.3 Nozzle size flow at 45 psi" on page 7.10. |
| Defect | Use | Defect | Use | Use | Reduced performance | Setup new size when changing nozzle, see "Menu 3.4.3 Nozzle size flow at 45 psi" on page 7.10 |
| Use | Use | Use | Defect | Use | Spray at constant speed | Keep sprayer at constant driving speed. |
| | | | | | | Type in simulated sprayer speed, "Menu 3.4.2 Simulated speed value" on page 7.9. |
| Ignore | Defect | Defect | lgnore | Use | Manual only | Adjust pressure after mechanical pressure gauge. |
| Ignore | lgnore | Ignore | Ignore | Defect | Manual only. Regulation valve can pass end stop. I.e. when continuing after it was closed, it opens again. | Adjust pressure after mechanical pressure gauge. |
| | | | | | | Check for passing end stop of valve. |
| | | | | | | Compensate for sections change. |

Fluid system test

- 1. Close the main ON/OFF valve.
- 2. Close the regulation valve by pressing (+) button to increase the pressure. Yellow diode lights on the regulation valve.
- 3. Close the agitation valve.
- 4. Close the pressure filter bypass valve.
- 5. Set pump from 250 to 300 RPM, engine in idle speed.
- 6. Now all water from pump should pass boom flow sensor.
- 7. Pump condition and possible internal valve leakages can be checked by comparing:
- Menu 4.5.5.3.3 Pump calc flow. This menu shows the calculated flow from the pump.
- Menu 4.5.5.3.6 Meas boom flow. This menu shows the actual measured flow through the flow sensor.

Testing and fine tuning

Fine tuning the flow constant - PPU

Calibration of the flow transducer is carried out with clean water but small changes may occur when adding pesticides or fertilizer. This will effect the final readings. This is typically noted when the volume displayed on the display does not equal the actual known volume that was sprayed out. The formula below can be used to "fine tune" the flow transducer PPU.

New PPU = $\frac{\text{Original PPU} \times \text{Displayed Volume}}{\text{Sprayed Volume}}$

For example, the spray tank is filled with 1000 gallons of spray liquid.

When sprayed out, the display showed a total of 900 gallons. (Original PPU = 485.0)

New PPU = $\frac{485.0 \text{ PPU} \times 900 \text{ Gallons}}{1000 \text{ Gallons}} = 436.5 \text{ PPU}$

Note the relation is inverse:

- To raise the displayed volume, the PPU is lowered.
- To lower the displayed volume, the PPU is raised.

Pin & Wire connection

| AMP Super Seal | Вох | Color coding |
|----------------|----------|--------------|
| 1 | Negative | Black |
| 2 | Positive | Brown |
| 3 | Signal | Blue |



12 - Testing and fine tuning

Testing flow transducer

- BROWN wire to positive of 12 volt battery.
- BLACK wire to negative.
- BLUE wire to multimeter positive.
- 1. Check the rotor turns freely.
- 2. Each vane in the rotor has a magnet in it with the pole facing out. Check that the 4 magnets are present.
- 3. Use a magnet to check that every second magnet in the rotor has the same pole orientation. The rotor magnets must be N S N S.
- 4. Connect negative from multimeter to negative of battery.
- 5. Set multimeter to DC volt.
- 6. By turning the mill wheel slowly, this will register approximately 8.0 +/- 1 volt with the diode on and 0.3 +/- 0.1 volt with the diode off with every second magnet.

Testing speed transducer

This transducer is used for speed, Twin speed, Boom fold, SafeTrack, Main pump/FlexCapacity RPM.

- BROWN wire to positive of 12 volt battery.
- BLACK wire to negative.
- BLUE wire to multimeter.
- 1. Connect negative from multimeter to negative of battery.
- 2. Set multimeter to DC volt.
- 3. Bring a metallic object within 1/8" to 3/16" (3 to 5 mm) from the transducer. This will register 1.4 +/- 0.2 volt and the diode will turn on.
- 4. By removing the object, this will register 12.0 +/- 1.0 volt. Diode is OFF.

Specifications

Specifications

| Supply voltage: | 12 Volt DC |
|--|---------------------------------|
| Controlled shutdown "low battery": | 9 Volt DC |
| Maximum supply: | 16Volt DC |
| Maximum peak: | 28 Volt DC |
| Ambient temperature: | 23°F to 158°F (– 5°C to + 70°C) |
| Memory: | Flash PROM non-volatile |
| Digital transducers (option 2, 3 and 4): | Square signal |
| Frequency: | 0.5 Hz to 2 kHz |
| Trigger high: | 4.0 to 12.0 Volt DC |
| Trigger low: | 0.0 to 2.0 Volt DC |
| Analog transducers (option 1): | |
| Supply: | 12 V |
| Input: | 4 to 20 mA |
| Minimum speed for volume regulation | 0.3 mph (0.5 km/h) |

Flow ranges for the flow transducers

| Housing | ousing Housing identification (A | | Orifice | PPU |
|---------|----------------------------------|--------|---------|--------|
| | | gpm. | mm | value |
| S/67 | One outside groove | 2-30 | 13.5 | 485.00 |
| S/67 | No groove | 4-70 | 20.0 | 225.00 |
| S/67 | Two outside grooves | 20-160 | 36.0 | 60.00 |

Pressure drop over 13.5 mm orifice is 15 psi at 40 gpm.

13 - Technical specifications

Electrical connections

Types of plugs and fuses

Fuses are located into the JobCom:

- 15 A auto fuse
- TWIN versions also 2x10 A auto fuse.

Breakout PCB:

• 2x 10 A auto fuse.

DAH PCB:

• 10 A slow blow fuse.

Plugs

- AMP Super Seal 1.5 with 2 and 3 pins.
- 13 pin plug ISO 11446.
- DAH: DB25F and DB37F connector.
- 13 pin ISO 11446M.
- ISOBUS: 9 pin IBBC F connector.

Materials and recycling

Disposal of electronics

Cardboard: Can recycle up to 99% and therefore should be put into the waste collection system.

Polyethylene: Can be recycled.

When the operating unit has completed its working life, it must be thoroughly cleaned. The synthetic fittings can be incinerated. The printed circuit boards and metallic parts can be scrapped.

Packaging information

Materials used for packaging are environmentally compatible. They can be safely deposited or they can be burnt in an incinerator.

13 - Technical specifications

Charts

Chart for recording values

| Menu | Function | 1 - Values | 2 - Values | 3 - Values |
|--------------------------|-----------|------------|------------|------------|
| [3.2.1 Flow constant] | Flow PPU | | | |
| [3.1.X.1 Speed constant] | Speed PPU | | | |
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Warranty policy and conditions

HARDI® NORTH AMERICA INC., 1500 West 76th Street, Davenport, Iowa, USA hereinafter called "HARDI®", offers the following limited warranty in accordance with the provisions below to each original retail purchaser of its own manufacturer, from an authorized HARDI® dealer that such equipment is at the time of delivery to such purchaser, free from defects in material and workmanship and that such equipment will be warranted for a period of one year from the time of delivery to the end user, providing the machine is used and serviced in accordance with the recommendations in the Operator's Manual and is operated under normal farm conditions.

1. This limited warranty is subject to the following exceptions:

a)This warranty will be withdrawn if any equipment has been used for purposes other than for which it was intended or if it has been misused, neglected, or damaged by accident, let out on hire or furnished by a rental agency. Nor can claims be accepted if parts other than those manufactured by HARDI® have been incorporated in any of our equipment. Further, HARDI® shall not be responsible for damage in transit or handling by any common carrier and under no circumstances within or without the warranty period will HARDI® be liable for damages of loss of use, or damages resulting from delay or any consequential damage.

- 2. We cannot be held responsible for loss of livestock, loss of crops, loss because of delays in harvesting or any other expense or loss incurred for labor, supplies, substitute machinery, rental for any other reason, or for injuries either to the owner or to a third party, nor can we be called upon to be responsible for labor charges, other than originally agreed, incurred in the removal or replacement of components.
- 3. The customer will be responsible for and bear the costs of:

a)Normal maintenance such as greasing, maintenance of oil levels, minor adjustments including the boom.

b)Transportation of any HARDI® product to and from where the warranty work is to be performed.

c)Dealer travel time to and from the machine or to deliver and return the machine from the service workshop for repair unless otherwise dictated by state law.

d)Dealer traveling costs.

- 4. This warranty will not apply to any product which is altered or modified without the express written permission of the HARDI® Service and Engineering Departments and/or repaired by anyone other than an Authorized HARDI® Dealer.
- 5. Warranty is dependent upon the strict observance by the purchaser of the following provisions:

a)That this warranty may not be assigned or transferred to anyone.

- b)That the Warranty Registration Certificate has been correctly completed by dealer and purchaser with their names and addresses, dated, signed and returned to the appropriate address as given on the Warranty Registration Certificate within 30 days of delivery to the purchaser.
- c)That all safety instructions in the operator's manual shall be followed and all safety guards regularly inspected and replaced where necessary.
- 6. No warranty is given on second-hand products and none is implied.
- 7. HARDI® reserves the right to incorporate any change in design in its products without obligation to make such changes on units previously manufactured.
- 8. The judgement of the HARDI® Service Department in all cases of claims under this warranty shall be final and conclusive and the purchaser agrees to accept its decisions on all questions as to defect and the repair or exchange of any part or parts.
- 9. No employee or representative is authorized to change this warranty in any way or grant any other warranty unless such change is made in writing and signed by the CEO in the Davenport office. Approval of warranty is the responsibility of the HARDI® Service Department.

14 - Warranty

- 10. Any warranty work performed which will exceed \$1000.00 <u>MUST</u> be approved <u>IN ADVANCE</u> by the Service Department. Warranty claims filed without prior approval will be returned.
- 11. Claims under this policy <u>MUST</u> be filed with the HARDI® Service Department within thirty (30) days of when the work is performed or warranty shall be void unless prior arrangements are made.
- 12. Parts which are requested for return by the HARDI® Service Department must be returned prepaid within thirty (30) days for warranty settlement.
- 13. Warranty claims must be COMPLETELY filled out including part numbers and quantities or claims will be returned to the submitting dealer.

DISCLAIMER OF FURTHER WARRANTY

THERE ARE NO WARRANTIES, EXPRESSED OR IMPLIED, EXCEPT AS SET FORTH ABOVE. THERE ARE NO WARRANTIES WHICH EXTEND BEYOND THE DESCRIPTION OF THE PRODUCT CONTAINED HEREIN. IN NO EVENT SHALL THE COMPANY BE LIABLE FOR INDIRECT, SPECIAL OR CONSEQUENTIAL DAMAGES (SUCH AS LOSS OF ANTICIPATED PROFITS) IN CONNECTION WITH THE RETAIL PURCHASER'S USE OF THE PRODUCT.



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